

· 过程的方向性.

(1) 第二定律:  $U, V$  固定,  $\Delta S \geq 0$ .

(2)  $T, V$  固定

$$\Delta F = \Delta U - T\Delta S = Q + W - T\Delta S$$

$$T, V \text{ fixed}, Q \leq T\Delta S \Rightarrow \Delta F \leq 0.$$

注: 指的是初始态和末态! (?) 这是因为  $\alpha \alpha = \int T \Delta S$  中.

$Q \leq T\Delta S$  是一个跳跃的公式!!  $T$  始终是环境温度! 只要环境温度不变即可.

(3)  $T, p$  固定

$$\Delta G = \Delta U - T\Delta S + p\Delta V = Q - T\Delta S = 0.$$

· 关键是要明白: 在有限性的系统中,  $U$  最小不是最佳的.

例如,  $F = U - TS$ , 有 "Energy" 和 "Entropic" term.

后者反映宏观力学过程的可逆性/大量粒子的统计性质

因此通常情况下,  $S$  要变大,  $F = U - TS$  同时是二者互斥, 于是简单的  $U_{\min} / S_{\max}$ .

这是合理的, 因为  $U_{\min}$  对应全部粒子到基态, 这与大量粒子的统计是相违背的.

· 麦克斯韦变子. (固定  $N$ )

$$dU = TdS - pdV$$

$$\left(\frac{\partial U}{\partial S}\right)_V = T \quad \left(\frac{\partial U}{\partial V}\right)_S = -p$$

$$\text{变换偏导数: } \frac{\partial^2 U}{\partial V \partial S} = \frac{\partial^2 U}{\partial S \partial V}$$

$$\Rightarrow \left(\frac{\partial T}{\partial V}\right)_S = -\left(\frac{\partial p}{\partial S}\right)_V. \text{ 剩下的以此类推.}$$

· 用处: 把不好观测的量转变为好观测的量.

· 例: 热容

$$C_V = \left(\frac{\partial U}{\partial T}\right)_V = T \left(\frac{\partial S}{\partial T}\right)_V$$

$$C_P = \left(\frac{\partial H}{\partial T}\right)_P = T \left(\frac{\partial S}{\partial T}\right)_P$$

理想气体:  $C_P - C_V = Nk_B$ . 一般情况如何?

$$S = S(T, p) = S(T, V(T, p))$$

$$\Rightarrow \left(\frac{\partial S}{\partial T}\right)_P = \left(\frac{\partial S}{\partial T}\right)_V + \left(\frac{\partial S}{\partial V}\right)_T \cdot \left(\frac{\partial V}{\partial T}\right)_P$$

$$C_P - C_V = T \underbrace{\left(\frac{\partial S}{\partial V}\right)_T}_{\text{不好测}} \cdot \underbrace{\left(\frac{\partial V}{\partial T}\right)_P}_{\text{可以测}}$$

代换:  $\left(\frac{\partial S}{\partial V}\right)_T$ , 找  $V(T)$  函数

$$\Rightarrow F = F(V, T) \quad dF = -SdT - pdV.$$

$$\left(\frac{\partial S}{\partial V}\right)_T = \left(\frac{\partial p}{\partial T}\right)_V.$$

$$C_P - C_V = T \cdot \underbrace{\left(\frac{\partial p}{\partial T}\right)_V \cdot \left(\frac{\partial V}{\partial T}\right)_P}_{\text{响应函数 Response function}}$$

· 膨胀率  $\text{Expansivity } \alpha = \frac{1}{V} \left(\frac{\partial V}{\partial T}\right)_P$

· 压缩系数  $\text{Compressibility } \kappa_T = -\frac{1}{V} \left(\frac{\partial V}{\partial p}\right)_T$ .

利用  $\left(\frac{\partial p}{\partial T}\right)_V \cdot \left(\frac{\partial T}{\partial V}\right)_P \cdot \left(\frac{\partial V}{\partial p}\right)_T = -1$ .

$$\left(\frac{\partial p}{\partial T}\right)_V = \left(\frac{\partial V}{\partial T}\right)_P / \left(-\frac{\partial V}{\partial p}\right)_T = \frac{V\alpha}{V\kappa_T} = \frac{\alpha}{\kappa_T}$$

代入 即有

$$C_p - C_v = \frac{V T \alpha^2}{k_T} \geq 0.$$

相平衡条件



把体系分割成均匀的子系统.

$$S = S(u, v, N) = \sum_a S^a(u^a, v^a, N^a)$$

现在要做的: 寻找  $u^a, v^a, N^a$ , 使熵  $S$  最大.

孤立体系约束条件:

$$\sum u^a = u, \quad \sum v^a = v, \quad \sum N^a = N.$$

条件极值  $\rightarrow$  拉格朗日乘子.

$$f(u, v, N) = \sum S^a(u^a, v^a, N^a) - \alpha \sum u^a - \beta \sum v^a - \gamma \sum N^a.$$

$f$  最大:

$$\begin{cases} \frac{\partial f}{\partial u^a} = 0 \Rightarrow \frac{\partial S^a}{\partial u^a} = \alpha \Rightarrow \frac{1}{T^a} = \alpha, \quad \forall a \\ \frac{\partial f}{\partial v^a} = 0 \Rightarrow \frac{\partial S^a}{\partial v^a} = \beta \Rightarrow \frac{p^a}{T^a} = \beta, \quad \forall a \\ \frac{\partial f}{\partial N^a} = 0 \Rightarrow \frac{\partial S^a}{\partial N^a} = \gamma \Rightarrow -\frac{\mu^a}{T^a} = \gamma, \quad \forall a \end{cases}$$

$$[ \alpha S = \frac{1}{T} \alpha u + \frac{p}{T} \alpha v - \frac{\mu}{T} \alpha N ]$$

因此, 在平衡态时:

$$\begin{cases} T_1 = T_2 = \dots = T, & \text{"thermal"} \\ p_1 = p_2 = \dots = p, & \text{"mechanical"} \\ \mu_1 = \mu_2 = \dots = \mu, & \text{"chemical"} \end{cases}$$

向平衡态的演化?



$T_1 > T_2$

$$S = S_1(u_1, v_1, N_1) + S_2(u_2, v_2, N_2)$$

$$\delta S = \frac{\partial S_1}{\partial u_1} \delta u_1 + \frac{\partial S_2}{\partial u_2} (-\delta u_1)$$

$$= \left( \frac{1}{T_1} - \frac{1}{T_2} \right) \delta u_1 > 0.$$

$$\frac{1}{T_1} < \frac{1}{T_2}, \quad \delta u_1 < 0. \Rightarrow \text{热量从高温流向低温.}$$

$$\text{同理, } \mu_1 > \mu_2 \Rightarrow \delta S = \left( -\frac{1}{T} + \frac{1}{T} \right) \delta N_1 > 0.$$

$\Rightarrow$  粒子数从高能态流向低能态.

平衡的稳定条件 [确定  $S$  是极大]

$$\sum_a \frac{\partial^2 S^a}{\partial x_i \partial x_j} \delta x_i \delta x_j \leq 0, \quad \{x_i\} = \{u^a, v^a, N^a\}.$$

Hessian Matrix: negative semi-definite 平衡态.

$$\frac{\partial}{\partial x_j} \left( \frac{\partial S^a}{\partial x_i} \right) \delta x_i \delta x_j$$

$\hookrightarrow$  "Force"  $J_i$ , 与  $x_i$  共轭

$$\frac{\partial J_i}{\partial x_j} \delta x_j = \delta J_i$$

$$\Rightarrow \delta J_i \delta x_i \leq 0, \text{ 对稳定的!} \quad [ \alpha S = \frac{1}{T} \alpha u + \frac{p}{T} \alpha v - \frac{\mu}{T} \alpha N ]$$

即  $\delta \left( \frac{1}{T} \right) \delta u + \delta \left( \frac{p}{T} \right) \delta v - \delta \left( \frac{\mu}{T} \right) \delta N \leq 0$ . [这里  $\delta^2 S$  是依据 Lagrange 乘子, 因为那些都是一阶的, 求二阶导之后都没有了]

$$-\frac{\delta T}{T} \delta U + \frac{T \delta P - P \delta T}{T^2} \delta V - \frac{T \delta \mu - \mu \delta T}{T^2} \delta N \leq 0.$$

极取  $\delta T$  项:

$$-\frac{\delta T}{T} (\delta U + P \delta V - \mu \delta N) + \frac{\delta P \delta V - \delta \mu \delta N}{T} \leq 0.$$

$$\Rightarrow \delta T \delta S - \delta P \delta V + \delta \mu \delta N \geq 0. \text{ for } \forall a.$$

这里确实是  $\forall a$ . 标准法书上有解释.

[理解: 选取三个独立变量做独立变动, 给另外三个, 代进去  $\geq 0$ ]

现在取  $\delta N = 0$ :  $N$  fixed

$$\delta T \delta S - \delta P \delta V \geq 0.$$

$$S = S(T, V) \quad P = P(T, V)$$

$$\delta T \left[ \left( \frac{\partial S}{\partial T} \right)_V \delta T + \left( \frac{\partial S}{\partial V} \right)_T \delta V \right] - \delta V \left[ \left( \frac{\partial P}{\partial T} \right)_V \delta T + \left( \frac{\partial P}{\partial V} \right)_T \delta V \right] \geq 0.$$

交叉项和 = 0

$$\Rightarrow \left( \frac{\partial S}{\partial T} \right)_V (\delta T)^2 - \left( \frac{\partial P}{\partial T} \right)_V (\delta V)^2 \geq 0.$$

$$\frac{C_V}{T} (\delta T)^2 + \frac{1}{V \kappa_T} (\delta V)^2 \geq 0.$$

稳定性要求:  $C_V > 0, \kappa_T > 0.$

另一种解释: 更子是线性的, 二阶通项下可以认为是独立的  
(这个结论/证, 今天没证, 忘了证了)

$$\begin{aligned} \delta T \delta S - \delta P \delta V + \delta \mu \delta N &= \delta T \delta S - \delta P \delta V + \delta N \cdot (-S \delta T + U \delta P) \\ &= N (\delta T \delta S - \delta P \delta V). \end{aligned}$$

$$\sum N^a (\delta T^a \delta S^a - \delta P^a \delta V^a) \geq 0$$

↓  
产量      ↓  
            温度

对给定的  $a$ : 把其他  $N^a$  取成 0, 得到

$$\delta T^a \delta S^a - \delta P^a \delta V^a \geq 0, \forall a$$

这有:

$$\delta T^a \delta S^a - \delta P^a \delta V^a + \delta \mu^a \delta N^a \geq 0, \forall a.$$

$f(x_i)$

$$\frac{\partial f}{\partial x_i} \delta x_i = 0 \Rightarrow \frac{\partial f}{\partial x_i} = 0, \forall i.$$

$$\frac{\partial^2 f}{\partial x_i \partial x_j} \delta x_i \delta x_j \geq 0.$$

$$\sum \lambda_i x_i = 0.$$

$$\frac{\partial f}{\partial x_i} \delta x_i + \mu (\sum \lambda_i \delta x_i) = 0 \quad \text{这个操作...?}$$

$$\Rightarrow \frac{\partial f}{\partial x_i} = -\mu \lambda_i.$$

$$df = 0.$$

$\Rightarrow f = \text{常数?}$

$\sum x_i$

$$\frac{\partial f}{\partial x_i} \delta x_i = 0.$$

$$F(x_1, \dots, x_n) = 0.$$

$$\lambda \cdot \sum \frac{\partial F}{\partial x_i} \delta x_i = 0$$

$$f(x_i) - \lambda \cdot F(x_i)$$

$$\left( \frac{\partial f}{\partial x_i} - \lambda \frac{\partial F}{\partial x_i} \right) \delta x_i = 0.$$

$$-F(x_i) \delta \lambda = 0$$

$$f(x_1, \dots, x_n, \lambda, x_n(\dots))$$

$$\frac{\partial f}{\partial x_i} + \frac{\partial f}{\partial x_n} \frac{\partial x_n}{\partial x_i} = 0.$$

$$\varphi(x_1, \dots, x_n) = 0$$

$$\frac{\partial \varphi}{\partial x_i} = 0$$

$$\frac{\partial x_n}{\partial x_i} = - \frac{\frac{\partial \varphi}{\partial x_i}}{\frac{\partial \varphi}{\partial x_n}}$$

$$\frac{\partial f}{\partial x_i} + \frac{\partial f}{\partial x_n} \frac{\partial \varphi}{\partial x_i} = \frac{\partial f}{\partial x_n} \frac{\partial \varphi}{\partial x_n}$$

$$\frac{\partial f}{\partial x_i} - \left( \frac{\frac{\partial f}{\partial x_n}}{\frac{\partial \varphi}{\partial x_n}} \frac{\partial \varphi}{\partial x_i} \right) = 0.$$

$$\lambda = \frac{\frac{\partial f}{\partial x_n}}{\frac{\partial \varphi}{\partial x_n}} \quad (\text{这题因为 } \varphi(\dots) = 0)$$

$$\begin{cases} \frac{\partial f}{\partial x_i} - \lambda \frac{\partial \varphi}{\partial x_i} = 0 \\ \frac{\partial f}{\partial x_n} - \lambda \frac{\partial \varphi}{\partial x_n} = 0 \end{cases}$$

$$\begin{aligned} \frac{\partial^2 f}{\partial x_i \partial x_j} &= \frac{\partial^2 f}{\partial x_i \partial x_j} + \frac{\partial^2 f}{\partial x_n \partial x_j} \frac{\partial x_n}{\partial x_i} \\ &= \frac{\partial^2 f}{\partial x_i \partial x_j} + \frac{\partial^2 f}{\partial x_n \partial x_j} \frac{\partial x_n}{\partial x_i} + \frac{\partial^2 f}{\partial x_n \partial x_n} \left( \frac{\partial \varphi}{\partial x_n} \frac{\partial x_n}{\partial x_i} \right) \\ &= \frac{\partial^2 f}{\partial x_i \partial x_j} + \frac{\partial^2 f}{\partial x_n \partial x_j} \frac{\partial x_n}{\partial x_i} + \frac{\partial^2 f}{\partial x_n \partial x_n} \frac{\partial \varphi}{\partial x_n} \frac{\partial x_n}{\partial x_i} \\ &= \frac{\partial^2 f}{\partial x_i \partial x_j} + \frac{\partial^2 f}{\partial x_n \partial x_n} \frac{\partial \varphi}{\partial x_n} \frac{\partial x_n}{\partial x_i} \end{aligned}$$

$\lambda$  乘出来交出来给  $\checkmark$