理论力学A

$\vec{F} = \frac{d\vec{p}}{dt} = \frac{d}{dt}(m\dot{\vec{r}}) = \frac{d}{dt}(m\frac{d\vec{r}(t)}{dt}\vec{e}_r) = \frac{d}{dt}(m\frac{dr}{dt})\vec{e}_r + m\dot{r}\dot{\vec{e}}_r$

$\Rightarrow m\ddot{r}\vec{e}_r + m\dot{r}^2\vec{e}_\theta = f(u)\vec{e}_r = m\dot{r}^2(\vec{e}_r + \vec{e}_\theta)$

开普勒问题：$f(r) = -\frac{k}{r^2}$，代入比耐公式得到 $\frac{d^2u}{d\theta^2} + u = \frac{m}{k}$，$u = \frac{m}{k} + A\cos\theta$

$r = \frac{1}{A\cos\theta + \frac{m}{k}} = \frac{p}{1+e\cos\theta}$，$p = \frac{k}{m}$，$e = pA$ $\Rightarrow$ 椭圆线、双曲线、抛物线

周期：f 和指数相关，$M \propto f \propto r^n$ $\propto a^{n+3}b$ $T \propto \frac{ab}{v}$ $\propto \frac{ab}{a^{\frac{n+1}{2}}}$ $\propto a^{\frac{n+3}{2}}$

LRL矢量：$\vec{A} = \vec{p}\times\vec{M} - mk\frac{\vec{r}}{r}$ $= const$

证明守恒：$\frac{d\vec{A}}{dt} = \frac{d\vec{p}}{dt}\times\vec{M} + \vec{p}\times\frac{d\vec{M}}{dt} - mk\frac{d}{dt}(\frac{\vec{r}}{r})$

第一项：$\frac{d\vec{p}}{dt} = -\frac{k}{r^2}\vec{r}$，$\vec{M} = m\vec{r}\times\dot{\vec{r}}$，$-\frac{k}{r^2}\vec{r}\times(\vec{r}\times\dot{\vec{r}}) = -\frac{k}{r^2}(\vec{r}(\vec{r}\cdot\dot{\vec{r}}) - \dot{\vec{r}}(\vec{r}\cdot\vec{r})) = \frac{k}{r}\dot{\vec{r}} - \frac{k}{r^3}\vec{r}(\vec{r}\cdot\dot{\vec{r}})$

第二项：M 守恒，$\frac{d\vec{M}}{dt} = 0$ 第三项：$-mk\frac{d}{dt}(\frac{\vec{r}}{r}) = -mk\frac{\dot{\vec{r}}}{r} + \frac{mk}{r^2}\vec{r}\dot{r} = -mk\frac{\dot{\vec{r}}}{r} + \frac{mk}{r^3}\vec{r}(\vec{r}\cdot\dot{\vec{r}})$

LRL矢量的作用：i) 看到 $\vec{M}$，ii) 判断 $\vec{r}_{min}$

i) $\vec{A}\cdot\vec{M} = (\vec{p}\times\vec{M} - mk\frac{\vec{r}}{r})\cdot\vec{M} = (\vec{p}\times\vec{M})\cdot\vec{M} - mk\frac{\vec{r}}{r}\cdot(\vec{r}\times\dot{\vec{r}}) = 0$

ii) 考虑近日点处，$\vec{A} = \frac{M^2}{mk}\vec{r}_{min} - \frac{m\dot{r}}{k}\vec{r}_{min}$ // $\vec{r}_{min}$

LRL矢量的大小：$\vec{A}\cdot\vec{r} = A r\cos\theta = (\vec{p}\times\vec{M})\cdot\vec{r} - mkr = \vec{M}\cdot(\vec{r}\times\vec{p}) - mkr = M^2 - mkr$

$\Rightarrow r = \frac{M^2}{mk + A\cos\theta} = \frac{\frac{M^2}{mk}}{1+\frac{A}{mk}\cos\theta}$ $\Rightarrow A = mke$

LRL矢量的对称性：属于动能为常数形式(1)的对称性，而非对心的质点对称性

引入无穷小量旋转：$\vec{r}' = \vec{r} + [\delta\vec{\varphi}(\vec{r}\cdot\vec{\omega}) - \vec{r}(\vec{\rho}\cdot\vec{\omega}) - \vec{\omega}(\vec{r}\cdot\vec{\rho})] = \vec{r} + [\vec{\omega}\times(\vec{\rho}\times\vec{r}) + \vec{r}\times(\vec{\rho}\times\vec{\omega})]$

拉格朗日形式不变的条件：$\frac{\partial L}{\partial t} + \frac{d}{dt}\vec{s}(q\rho) = \frac{d}{dt}\alpha(q,t)$ $L = \frac{1}{2}m\dot{r}^2 - V$

第一项：$-\frac{k}{r}\vec{r}\cdot[\vec{\omega}\times(\vec{p}\times\vec{r}) + \vec{r}\times(\vec{p}\times\vec{\omega})] = -\frac{k}{r}(\vec{p}\times\vec{r})\times\vec{\omega}$

$= m\dot{\vec{r}} - \frac{(\vec{r}\cdot\vec{p})}{r^2}\vec{r})\times\vec{\omega} = \frac{d}{dt}(m\vec{r})\times\vec{\omega}$

第二项：$m\ddot{\vec{r}}\cdot[\vec{\omega}\times(\vec{p}\times\vec{r}) + \vec{r}\times(\vec{p}\times\vec{\omega})] + \vec{p}\cdot[\vec{\omega}\times(\vec{r}\times\dot{\vec{r}}) + \dot{\vec{r}}\times(\vec{r}\times\vec{\omega})]$

$= [(\vec{p}\times\vec{r})\times\vec{p} + (\vec{p}\times\vec{r})\times\vec{r}]\cdot\vec{\omega} = \frac{d}{dt}(\vec{r}\times\vec{p})\cdot\vec{\omega} = \frac{d}{dt}(\vec{r}\times\vec{M})\cdot\vec{\omega}$

$\Rightarrow -\delta\lambda = (\vec{p}\times\vec{M} - mk\frac{\vec{r}}{r})\cdot\vec{\omega}$，由诺特定理：$\vec{p}\cdot\vec{\omega} + \delta\lambda = const$

$\vec{p}\cdot[\vec{\omega}\times(\vec{p}\times\vec{r}) + \vec{r}\times(\vec{p}\times\vec{\omega})] = (\vec{r}\times\vec{r})\times\vec{p}\cdot\vec{\omega} = 2\vec{p}\times\vec{M}\cdot\vec{\omega}$ $\Rightarrow \vec{p}\times\vec{M} - mk\frac{\vec{r}}{r} = const$

无穷小量旋转的四元素：$\alpha_j = -\omega_j[A_j, q_i] = -\omega_j\frac{\partial A_j}{\partial q_i}$ $= -\omega_j(\frac{\partial p}{\partial q_i}q_j - q_i p_j - (\vec{r}\cdot\vec{p})\delta_{ij})$

$\alpha p_i = -\omega_j[A_j, p_i]$，验证投影 $\vec{r}$ 的 $\omega_j[A_j, H] = 0$，$\Rightarrow A$ 为守恒量，$[A, H] = 0$

有心力下的质点运动轨道：$M = mr^2\dot{\varphi}$，$E = \frac{1}{2}m\dot{r}^2 + \frac{M^2}{2mr^2} + V(r)$

$dt = \frac{m\dot{r}}{M}dr$ $\Rightarrow dt = \frac{dr}{\sqrt{\frac{2}{m}(E - V(r)) - \frac{M^2}{m^2r^2}}}$ $\Rightarrow \int d\varphi = \int\frac{\frac{M}{r^2}dr}{\sqrt{\frac{2m}{M^2}(E-V(r)) - \frac{m^2}{M^2r^2}}}$

eg. 由于地球质量远大于卫星质量，卫星绕地球运动的轨道可视为静止的地球为参考系，卫星绕地球运动的轨道为椭圆，求椭圆的半长轴和半短轴的长度之比。

$\frac{mv^2}{r} = \frac{GMm}{r^2}$ $\Rightarrow v_1 = \sqrt{\frac{GM}{r_0}}$，$M = \pi ab$，$\dot{M} = \frac{\pi}{2}b\sqrt{2am}\dot{r} = \sqrt{\frac{\pi}{2}m}b\dot{r}$ $\Rightarrow p = \frac{b^2}{a}$

$E = \frac{1}{2}m(v_1\dot{r})^2 - \frac{GMm}{r_0} = -\frac{GMm}{2a}$ $\Rightarrow a = r_0$，$b = \frac{\sqrt{2}}{2}r_0$，$c = \frac{\sqrt{2}}{2}r_0$ $\Rightarrow e = \frac{\sqrt{2}}{2}$

$r = \frac{\frac{b^2}{a}}{1+\frac{c}{a}\cos(\theta+\pi)}$ $\Rightarrow \theta_0 = \cos^{-1}\frac{\sqrt{2}}{2}$

由对称性，当星际飞船在椭圆上到地球的距离为 r_0 时，飞船沿切线方向和 r_0 垂直，即从切线发射一颗人造卫星与星星

发射速度最小为多少？ $A = \frac{M^2}{m^2} = \frac{a\dot{s}}{m^2}$

能量比较：$\frac{1}{2}mv_0^2 - \frac{GMm}{r_0} = \frac{1}{2}mv^2$ 万有引力：$\frac{v^2}{r_0} = \frac{GM}{r_0^2}$，$v_0 = \sqrt{\frac{GM}{r_0}}$

$2a = 1.5r_0$ $E = -\frac{GMm}{1.5r_0} = \frac{1}{2}mv^2 - \frac{GMm}{r_0}$ $\Rightarrow v' = \sqrt{\frac{4}{3}\frac{GM}{r_0}}$

$v_{min} = \sqrt{\frac{2GM}{r_0}} - \sqrt{\frac{4}{3}\frac{GM}{r_0}} = \sqrt{\frac{2-\sqrt{\frac{4}{3}}}{r_0}GM} = 0.293\sqrt{\frac{GM}{r_0}}$

e. 在地球上以第三宇宙速度 v_0 沿与太阳连线发射一飞行（脱离地球引力范围，进入太阳系），求飞船轨道。

$\frac{1}{2}mv_0^2 + V_{eff}(r_0) = E = 0$，$E = \frac{1}{2}m\dot{r}^2 + V_{eff}(r)$ $\Rightarrow \dot{r} = v_0$ 即飞船在地球处速度为 v_0

$J = \sqrt{GMr_0} = \sqrt{mpk}$ $\Rightarrow p = r_0$，$e = 1$

自锁条定理：有心力场下质点运动具有稳定闭合轨道的条件

$\frac{d^2u}{d\varphi^2} + u = J(u) = -\frac{f(\frac{1}{u})}{mJ^2u^2}$ 圆周运动，$u_0 = J(u_0)$，

考虑微扰，$\delta u = u - u_0 = \frac{1}{r} - u_0 = J(u_0+\delta) - J(u_0) = J'(u_0)\delta + O(\delta^2)$

$\Rightarrow \frac{d^2\delta}{d\varphi^2} + (1 - J'(u_0))\delta = 0$，$\beta^2 = 1 - J'(u_0)$

i) $\beta^2 > 0$，轨道稳定在某个圆附近 ii) $\beta^2 = 0$，轨道发散或螺线

若轨道闭合，β 需为有理数，$J(u) = -\frac{f(\frac{1}{u})}{mJ^2u^2}$ $u_0 = -\frac{f(\frac{1}{u_0})}{mJ^2u_0^2}$

$J'(u_0) = \frac{f(\frac{1}{u_0})}{mJ^2u_0^2} - \frac{m}{mJ^2u_0^2}\frac{df(\frac{1}{u})}{du}\Big|_{u=u_0} = -2 + \frac{u_0}{f(\frac{1}{u_0})}\frac{df(\frac{1}{u})}{du}\Big|_{u=u_0}$

$\beta^2 = 3 - \frac{u_0}{f(\frac{1}{u_0})}\frac{df(\frac{1}{u})}{du}\Big|_{u=u_0}$ 再次说明各有对应不同 u_0 确定，$\Rightarrow \beta^2$ 为常数

$\frac{df}{dr} = (\beta^2-3)\frac{f}{r}$ $\Rightarrow f(r) = -k r^{\beta^2-3}$ 幂次为零或负整数

考虑 $J(u)$ 的更高阶项对轨道的影响

$\frac{d^2\delta}{d\varphi^2} + \beta^2\delta = \frac{1}{2}J''(u_0)\delta^2 + \frac{1}{6}J'''(u_0)\delta^3 + O(\delta^4)$

$\delta = \delta_0 + \delta_1\cos\beta\varphi + \delta_2\sin\beta\varphi + \delta_3\cos 2\beta\varphi$，代入方程，比较系数，$\delta_3$ 最小，阶小量

$\begin{cases}\cos\beta\varphi: & \beta^2\delta_1 = \frac{1}{2}J''(u_0)\delta_0\delta_1 + \frac{1}{2}J''(u_0)\delta_2\delta_3 \\ \cos 2\beta\varphi: & 0 = \frac{1}{2}J''(u_0)(\frac{1}{2}\delta_1^2 + \frac{1}{2}\delta_2^2) + \frac{1}{6}J'''(u_0)\cdot\frac{1}{2}\delta_1^2 \\ \cos 3\beta\varphi: & -9\beta^2\delta_3 = \frac{1}{2}J''(u_0)\frac{1}{2}\delta_1^2 + \frac{1}{6}J'''(u_0)\frac{1}{2}\delta_1^3\end{cases}$ 取 δ_0 为阶小量，δ_1 为三阶小量

$J(u_0) = f(\frac{1}{u_0})\frac{u_0}{mJ^2} = \frac{k}{m}u_0^{\beta^2}$，$J'(u_0) = \frac{k}{m}u_0^{\beta^2-1}$，$J''(u_0) = \frac{k}{m}u_0^{\beta^2-2} = 0$ $\Rightarrow J'''(u_0) = u_0^{\beta^2}u^{\beta^2-3}$

$J'(u_0) = (1-\beta^2)u_0^{\beta^2}u^{\beta^2}$，$J''(u_0) = -\beta^2(1-\beta^2)u_0^{\beta^2}u^{\beta^2-1}$，$J'''(u_0) = \beta^2(1-\beta^2)(\beta^2-2)u_0^{\beta^2}u^{\beta^2-2}$

代入方程得：$\delta_0 = -\frac{(1-\beta^2)}{4\beta^2}\delta_1^2$，$\delta_2 = \frac{(1-\beta^2)}{12\beta}\delta_1^3$，代入验证成立，$\beta^2(1-\beta^2)(1-\beta^2) = 0$

$\Rightarrow \begin{cases}\beta^2 > 1 & \text{不稳定} \\ \beta^2 = 0 & \text{不对应轨道} \\ \beta^2 = 1 & \text{对应轨道稳定}\end{cases}$ $J'(u_0) = 0$，$J''(u_0) = \frac{k}{m}u_0^{\beta^2}$，$\cdots$ 都对应轨道

$\beta^2 = 1$ 对应轨道稳定，称为自锁条件，轨道闭合

微分角动量积分：$2r\cos\theta\,\sigma(\theta)d\theta = 2\pi\rho d\rho$ $\Rightarrow \sigma(\theta) = \frac{\rho}{2\cos\theta}\left|\frac{d\rho}{d\theta}\right|$

总散射截面 $\sigma_{tot} = \int_0^{\pi/2}\sigma(\theta)\cdot 2\pi\sin\theta\,d\theta$

$\theta(\rho) = \pi - 2\varphi = \pi - 2\int_0^{u_{max}}\frac{M}{\sqrt{2m(E-V)-\frac{M^2}{r^2}}}du$ $M = mv_0\rho$，$E = \frac{1}{2}mv_0^2$

$= \pi - 2\int_0^{u_{max}}\frac{\rho\,du}{\sqrt{1-\frac{\rho^2}{r^2}-\frac{V}{E}}}$

eg. 有斥力的问题，质点的初始动量为 p_0，瞄准距离为 ρ，求散射截面

$V = ku$，$E = \frac{1}{2}mv^2 = \frac{k^2}{2E}$，$M = mv_0\rho = \sqrt{2mk}$ $p^2 = \frac{m^2v_0^2}{2}\rho^2 = \frac{2E^2}{k^2}\rho^2 = (e^2-1)\rho^2 = \frac{1}{2E}(e^2-1)$

$\Rightarrow e = \sqrt{1+(\frac{2E}{k})^2}$，$\cos\varphi = \cos(\frac{\pi}{2}-\frac{\theta}{2}) = \sin\frac{\theta}{2} = \frac{1}{\sqrt{1+(\frac{2E}{k})^2}}$，$\cot\frac{\theta}{2} = \frac{2E}{k}\rho$

$\Rightarrow \sigma(\theta) = \frac{1}{4}(\frac{k}{2E})^2\frac{1}{\sin^4\frac{\theta}{2}}$，$\sigma_{tot} = \pi\int_0^{\pi}\sigma(\theta)\sin\theta\,d\theta = \infty$

eg. 势能满足 $V = \begin{cases}0 & r > a \\ \infty & r < a\end{cases}$ 下的散射截面

$\theta(\rho) = \pi - 2\int_0^{u_{max}}\frac{\rho\,du}{\sqrt{1-\frac{u^2}{\rho^2}}} = \pi - 2\int_0^{u_{max}}\frac{du}{\sqrt{\frac{1}{\rho^2}-u^2}} = \pi - 2\arccos(\frac{\rho}{a})$

$\cos\frac{\theta}{2} = \frac{\rho}{a}$，$-\sin\frac{\theta}{2}d\theta = \frac{d\rho}{a}$ $\Rightarrow \sigma(\theta) = \frac{\rho}{2\sin\theta}$ $\sigma_{tot} = \int_0^{\pi}2\pi\cdot\sin\theta\,\sigma(\theta)\,d\theta = \pi a^2$

eg. 刚性球，$U(r) = \begin{cases}-U_0 & r < a \\ 0 & r > a\end{cases}$，$a > 0$，$U_0 > 0$，$\sigma_{tot}$ 是什么量？

i) 当粒子质点运动方程 $\begin{cases}J = mr^2\dot{\varphi} \\ E = \frac{1}{2}m\dot{r}^2 - \frac{GMm}{r} - U_0\frac{a^2}{r^2}\end{cases}$

ii) 结合系统一维等效势，轨道存在不同的能量和初始条件，运动轨道和特性

$V_{eff} = \frac{J^2}{2mr^2} - U_0\frac{ma^2}{r^2}$

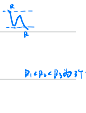
$\frac{dV_{eff}}{dr} = -\frac{J^2}{mr^3} - U_0\frac{2a^2}{r^3}(-\frac{1}{2}r - 1) = \frac{1}{r^3}[\frac{J^2}{m} + 2U_0a^2(r+\frac{a}{2})]$

$f(r) = U_0a^2(r+\frac{a}{2})$，$f(r) = U_0a^2(-\frac{1}{2}r+1) + U_0a^2(r+\frac{a}{2}) = U_0a^2(-\frac{1}{2}r+1)$ $\Rightarrow r = \frac{1}{1.5}r_0$

$f(r)$ 为一次函数，在 $r = \frac{1}{1.5}r_0$ 取到 $f(r) = 0$

i) $J > \sqrt{mf(r_0)}$，$V_{eff} < 0$，V_{eff} 上，总能在 $r > 0$ 处运动，$\frac{J^2}{2mr^2} - \frac{a}{r} = E$

ii) $J < \sqrt{mf(r_0)}$，r_1, r_2 是方程 $f(r) = \frac{J^2}{m}$ 的两根，$r < r_1$



i) $V_{eff}(r) > 0$，动量 $E > V_{eff}(r_0)$ 或 $E < V_{eff}(r)$ 时，粒子能在 $r > a$ 区域运动

ii) $V_{eff}(r) = E < V_{eff}(r_0)$ 时，$r > r_2$ 或 $r < r_1$ 时，粒子能在 $r > a$ 区域运动

iii) $V_{eff}(r) = 0$，当 $E > V_{eff}(r_0)$ 时，总能在 $r > a$ 处运动

当 $0 < E < V_{eff}(r_0)$ 时，$r < r_1$ 或 $r > r_2$ 内粒子能运动，$r > r_1$ 粒子能运动 $r < r_2$ 粒子能运动

当 $E < 0$ 时，总能在 $r < r_2$ 内粒子能运动

(2) 稳定运动的圆轨道，即圆周运动轨道：

$mi = \frac{1}{r^2}[\frac{J^2}{m} - U_0a^2(r+\frac{a}{2})]$

$\frac{J^2}{m} = U_0a^2(r_0+\frac{a}{2}) = \frac{mv_0^2}{2}r_0^2$ $mv_0^2 = \frac{U_0a^2}{mr_0^2}(1+\frac{a}{r_0})$

$\omega_0^2 = \frac{1}{mr_0}[\frac{J^2}{m} - U_0a^2(r_0+\frac{a}{2})^{-1}] = \frac{1}{mr_0}[\frac{J^2}{m} - U_0a^2(\frac{1}{r_0} - \frac{a}{2r_0^2} + \cdots)] = \frac{U_0a^2}{mr_0^3}(1+\frac{a}{2r_0})$

小振动：

$L = \frac{1}{2}m_{ij}\dot{q}_i\dot{q}_j - \frac{1}{2}k_{ij}q_iq_j$ m_{ij} 是正定阵，

运动方程：$m_{ij}\ddot{q}_j + k_{ij}q_j = 0$ $q_j(t) = A_j\exp(i\omega t)$，假设其为同一开始角 ω，

$(-m_{ij}\omega^2 + k_{ij})A_j = 0$ $A = \begin{pmatrix}A_1\\A_2\\\vdots\\A_n\end{pmatrix}$ 有非零解 $\det(k - \omega^2 M) = 0$

矩阵 A^{ij} 本身与 ω_i 对应 ω_j，则不妨假设为 $\begin{pmatrix}a_1^{(1)}\\a_2^{(1)}\\\vdots\\a_n^{(1)}\end{pmatrix}$ 其中 a_i 为第 i 个振动的幅度系数

$\dot{r} = \frac{dr}{dt} = \frac{dr}{d\varphi}\frac{d\varphi}{dt} = \frac{dr}{d\varphi}\frac{M}{mr^2}$ $\Rightarrow d\varphi = \frac{M}{r^2}\frac{dr}{\dot{r}} = \frac{M}{r^2}\frac{dr}{\sqrt{\frac{2}{m}(E-V)-\frac{M^2}{mr^2}}}$

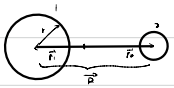
$\theta = \pi - 2\int_0^{u_{max}}\frac{\rho\,du}{\sqrt{1-\frac{\rho^2}{r^2}-\frac{V}{E}}}$ $= \pi - 2\int_0^{u_{max}}\frac{\rho\,du}{\sqrt{1-\rho^2u^2-\frac{V}{E}}}$ ？u=cosφ，计算是有不对应 能量是这样的函数对应的另外的，做为自锁条件的约束 $\frac{\rho}{r} = u$

$\frac{\pi}{2} - \frac{\theta}{2} = \arccos\frac{\frac{\rho}{r_0}}{\sqrt{1+\frac{2E}{k}r_0^2}} + \arcsin\frac{\sqrt{1+\frac{2E}{k}r_0^2}}{\sqrt{1+\frac{4E}{k}r_0^2}}$ 证一般：$\sin^{-1}(0) = \frac{\pi}{2}\Delta$，$0 = \cos\Delta$，$\Delta$ 为常数

$\Rightarrow \frac{\theta}{2} = \frac{\frac{\rho}{r_0}}{\sqrt{1+\frac{2E}{k}r_0^2}}$，$\beta^2 = (1+\frac{2E}{k}r_0^2)\frac{\rho^2}{r_0^2}$，$\beta^2 = \tan^2\frac{\theta}{2}(1-\frac{\rho^2}{r_0^2})$

$\frac{\rho^2}{r_0^2} = \tan^2\frac{\theta}{2}(1-\frac{\rho^2}{r_0^2})$ $\Rightarrow \rho = \frac{r_0}{\sec}\cos^2\frac{\theta}{2}(1+\frac{\rho^2}{r_0^2})$

$\Rightarrow \frac{\rho^2}{r_0^2} = \frac{\cos^2\frac{\theta}{2}}{1-\cos^2\frac{\theta}{2}}$



演化为无穷远 位移角速度 $\omega^2 = \frac{Gm_1(m_1+m_2)}{R^3}$

$m_1\omega^2r_1 = \omega^2\frac{m_1m_2}{m_1+m_2}R = \frac{Gm_1m_2}{R^2}$

重力场势能：$U(r) = -\frac{Gmm_1}{r} - \frac{Gmm_2}{|R-r|} - \frac{1}{2}m\omega^2(\vec{r}\cdot\vec{r})$

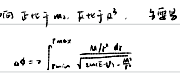
考虑 $R \gg r$，$\frac{1}{|R-r|} = (R^2+r^2-2R\vec{r})^{-\frac{1}{2}} = \frac{1}{R}(1+\frac{r^2}{R^2}-\frac{2\vec{R}\cdot\vec{r}}{R^2})^{-\frac{1}{2}} = \frac{1}{R}(1-\frac{r^2}{2R^2}+\frac{3}{8}\frac{(2\vec{R}\cdot\vec{r})^2}{R^4} - \frac{3}{2}\frac{2\vec{R}\cdot\vec{r}}{R^2})$

$\Rightarrow U(r) = \frac{Gmm_1}{r} - \frac{Gmm_2}{R}(1 - \frac{\vec{R}\cdot\vec{r}}{R^2} + \frac{3}{2}\frac{(\vec{R}\cdot\vec{r})^2}{R^4} - \frac{1}{2}\frac{r^2}{R^2}) - \frac{1}{2}m\omega^2(r^2+R^2) - m\vec{v}\cdot\vec{r}$ 消去

$= \frac{Gmm_1}{r} - \frac{Gmm_2}{R} - \frac{1}{2}m\omega^2(r^2-R^2)$ $(\frac{Gmm_2}{R^3} = \omega^2R)$

i) 一不小心，由于地球偏离，有两次极值分布 (R-r) 有两次到对称值

ii) 潮汐力的影响 正比于 m_2，反比于 R^3，与重力地球比较的影响



面积定理：$\sigma\Phi = \int_{r_{min}}^{r_{max}}\frac{M/r^2\,dr}{\sqrt{2m(E-V)-\frac{M^2}{r^2}}}$

考虑 $V_{eff} = V_0(r) + \delta V(r)$，$\sigma\Phi = \sigma\pi - \delta\Phi$

$\delta\Phi = 2\int_{r_{min}}^{r_{max}}\frac{\partial}{\partial V}\frac{M/r^2\,dr}{\sqrt{2m(E-V)-\frac{M^2}{r^2}}}\Big|_{V=V_0}\delta V = 2\int_{r_{min}}^{r_{max}}\frac{m}{M}\frac{\partial}{\partial(\frac{1}{r})}\frac{dr}{\sqrt{2m(E-V)-\frac{M^2}{r^2}}}\Big|_{V=V_0}\delta V$

$= 2m\int_{r_{min}}^{r_{max}}\frac{\delta V(r)\,dr}{\sqrt{2m(E-V)-\frac{M^2}{r^2}}}$

eg. 质量运动问题，假设简化：质量均匀分布在球面上

$\delta V(r) = -\int_{-\pi}^{\pi}\frac{Gm_1m}{\pi a}\frac{ad\alpha}{\sqrt{R^2+a^2-2aR\cos\alpha}} = -\int_0^{\pi}\frac{Gm_1m}{\pi R}(1+\frac{a^2}{R^2}-2\frac{a}{R}\cos\alpha)^{-\frac{1}{2}}d\alpha$ $a \ll r$

$= -\frac{Gm_1m}{R}(1+\frac{1}{2}\frac{a^2}{R^2}+\cdots)$ $\delta V(r) = -\frac{Gm_1m}{R}\frac{a^2}{R^2}$

$\delta\Phi = 2m\frac{\partial}{\partial M}\int_{r_{min}}^{r_{max}}\frac{\frac{GMm_1}{R}\frac{r^2}{R^2}dr}{\sqrt{2m(E+\frac{GMm}{r})-\frac{M^2}{r^2}}} = -\sqrt{\frac{m}{2E}}\frac{Gm_1m}{R^3}2\pi\int_{r_{min}}^{r_{max}}\frac{r^3dr}{\sqrt{(r-r_{min})(r_{max}-r)}}$

令 $a = \frac{r_{max}-r_{min}}{2}$，$c = \frac{r_{max}+r_{min}}{2}$ $I_{nm} = \int_{-a}^{a}\frac{(x+c)^n(a^2-x^2)^m}{\sqrt{a^2-x^2}}dx = \frac{\pi}{2}c^n$ $n=m=0$

$E = -\frac{k}{2a}$ $M = \sqrt{pkm} = \sqrt{a(1-e^2)pm}$ $= \sqrt{-\frac{mk^2}{2E}(1-e^2)}$ $\Rightarrow e = \sqrt{1+\frac{2EM^2}{mk^2}}$

$\frac{2a^3}{GM} = \frac{4\pi^2}{mk}$，$\frac{4\pi^2}{mk}(-\frac{mk^2}{2E})(1-e^2)$，$\delta\Phi = -\sqrt{\frac{m}{2E}}\frac{Gm_1m}{R^3}\frac{2\pi}{GM}\sqrt{\frac{mk^2}{2E}}\sqrt{1-e^2}$

$\Rightarrow \delta\Phi = \frac{3\pi}{2}\sqrt{1-e^2}(\frac{m}{M})(\frac{a}{R})^3$ 证：$\frac{m}{M}$ 为两个质量的质量比值，M 为质量，m_0 为不对应的

eg. 相对论效应造成的近日点进动

$L = m\sqrt{1-\frac{v^2}{c^2}}vr$ $\Rightarrow$ $L = \frac{1}{2}mv^2(1+\frac{v^2}{2c^2}+\cdots)r$ $v^2 = \dot{r}^2 + r^2\dot{\varphi}^2$

$M = p_\varphi = \frac{\partial L}{\partial\dot{\varphi}} = m\dot{r}^2\dot{\varphi}(1+\frac{v^2}{c^2})$ $p_r = \frac{\partial L}{\partial\dot{r}} = m\dot{r}(1+\frac{v^2}{2c^2})$

$E = E_k + V = \frac{1}{2}mv^2 - L = \frac{1}{2}mv^2(1+\frac{3v^2}{4c^2}) - \frac{k}{r}$

$\frac{1}{2}mv^2 = \frac{1}{2}m(\dot{r}^2+r^2\dot{\varphi}^2) = \frac{1}{2}m(\frac{p_r}{m}^2 + r^2) = \frac{1}{2}m(\frac{M}{mr^2}\dot{r})^2 + \frac{M^2}{2mr^2}(1-\frac{v^2}{c^2}) = \frac{M^2}{2mr^4}(\frac{dr}{d\varphi})^2(1-\frac{v^2}{c^2})$

$= \frac{M^2}{2m}(\frac{du}{d\varphi})^2 - \frac{1}{2}mv^2\frac{v^2}{c^2}$ $\Rightarrow E = \frac{M^2}{2m}(\frac{du}{d\varphi})^2 - \frac{1}{2}mv^2\frac{v^2}{c^2} - ku$

质点运动 $\frac{1}{2}mv_r^2 = E - V_{eff}$ $\Rightarrow \frac{dr}{dt} = -\frac{(E-V_{eff})^2}{mc^2}$

$E(1+\frac{E}{2mc^2}) + ku(1+\frac{E}{mc^2}) = \frac{M^2}{2m}(\frac{du}{d\varphi})^2(1+\frac{v^2}{c^2})$

$d\varphi = \frac{du}{\sqrt{\frac{2m}{M^2}(E+ku)-u^2}\sqrt{1+\frac{v^2}{c^2}}} = \frac{mdu}{\sqrt{E^2+2Eku+k^2u^2-A^2}}$ 令 $A^2 = 2mE(1+\frac{E}{2mc^2}) - m^2k^2$

$= \frac{mdu}{A} - \frac{mk}{A}\frac{du}{\sqrt{1-(\frac{ku+E}{A})^2}}$ $\Rightarrow \int\frac{mdu}{A} = \frac{mu}{A}$，$\int\frac{du}{\sqrt{1-x^2}} = -\frac{2\pi}{mk}$ $\Rightarrow \delta\varphi = -\frac{2\pi}{mk}\frac{mk^2}{A} = \frac{2\pi k}{A} = \frac{2\pi k}{\sqrt{2mE(1+\frac{E}{2mc^2})-m^2k^2}}$