

# 高等原子分子物理



自由电子发射  $e^- \rightarrow e^- + \gamma$  Xe:  $I_p(Xe) = 12.1298 eV$ ,  $\hbar\omega = 2.33 eV$ ,  $N = 6$  但测出  $N \gg 6$

切伦科夫辐射:  $u$  入射, 散射角  $\alpha$

$$\cos \alpha = \frac{c}{\sqrt{\epsilon_r} u} \left( 1 - \frac{\epsilon_r - 1}{2} \sqrt{1 - \frac{u^2}{c^2} \frac{\hbar\omega}{mc^2}} \right)$$

$$\epsilon_r = 1: \cos \alpha = \frac{c}{u} > 1 \quad \text{不能发射} \quad \text{水: 可以}$$

Above Threshold Ionization (ATI) 阈上电离

$$\text{能量 } U_p = \frac{e^2 E_0^2}{4m\omega^2} a.u. = \frac{E_0^2}{4\omega^2} \quad U_p = 0.22 a.u. = 5.99 eV, \quad \Delta t \sim \frac{\hbar}{\Delta E} \sim 0.5 a.u. \sim 12 as$$

HHG-ATI

$$t_0 \text{ 出生时刻} \quad E(t) = E_0 \sin \omega t, \quad v(t) = -\int_{t_0}^t E(t') dt', \quad x(t) = \int_{t_0}^t v(t') dt'$$

$$v(t) = \frac{E_0}{\omega} (\cos \omega t - \cos \omega t_0) \quad \text{第一项: oscillation} \quad \text{第二项: translation (drift)}$$

$$\text{驱动部分 } \frac{1}{2} m v_{drift}^2 = \frac{E_0^2}{2\omega^2} \cos^2 \omega t_0 = 2U_p \cos^2 \omega t \leq 2U_p$$

$$\text{Recollision } x(t) = \int_{t_0}^t v(t') dt' = -\frac{E_0}{\omega} (t - t_0) \cos \omega t_0 + \frac{E_0}{\omega^2} (\sin \omega t - \sin \omega t_0)$$

$$\text{回碰条件: } x(t_r) = 0 \implies (\omega t_r - \omega t_0) \cos \omega t_0 = \sin \omega t_r - \sin \omega t_0$$

$$t_0 \rightarrow t_r, t_r > t_0 \text{ 讨论可知仅可 } \frac{\pi}{2} \leq \omega t_0 < \pi \text{ 或 } \frac{3\pi}{2} \leq \omega t_0 < 2\pi$$

$$\text{速度分解} \begin{cases} v(t_r) = \frac{E}{\omega} (\cos \omega t - \cos \omega t_0) \\ v_{\parallel}(t_r) = v(t_r) \cos \theta \\ v_{\perp}(t_r) = v(t_r) \sin \theta \end{cases}, \text{ 之后}$$

$$\begin{cases} v_{\parallel}(t) = v_{\parallel}(t_r) + \int_{t_r}^t a(t') dt' = \frac{E}{\omega} (\cos \omega t_r - \cos \omega t_0) \cos \theta + \frac{E}{\omega} (\cos \omega t - \cos \omega t_r) \\ v_{\perp}(t) = v_{\perp}(t_r) = \frac{E}{\omega} (\cos \omega t_r - \cos \omega t_0) \sin \theta \end{cases}$$

$$\text{电子动能 } E_k(t) = \frac{1}{2} (v_{\parallel}^2(t) + v_{\perp}^2(t)), \text{ 即}$$

$$E_k(t) = \frac{E_0^2}{2\omega^2} [(\cos \omega t_r - \cos \omega t_0)^2 + (\cos \omega t - \cos \omega t_r)^2 + 2(\cos \omega t_r - \cos \omega t_0) \cos \theta (\cos \omega t - \cos \omega t_r)]$$

$$\text{令 } U_p = \frac{E_0^2}{4\omega^2}, \text{ 平均}$$

$$\langle E_k \rangle = 2U_p [(\cos \omega t_r - \cos \omega t_0)^2 + \frac{1}{2} + \cos^2 \omega t_0 - 2 \cos \theta (\cos \omega t_r - \cos \omega t_0) \cos \omega t_r]$$

$$\text{量子情形 } i \frac{\partial}{\partial t} \psi = \hat{H} \psi, \quad \hat{H} = \frac{1}{2} [p + A(t)]^2 - \varphi(x) = H_{pA}$$

$$\text{规范变换 } \psi(x, t) \rightarrow e^{i\chi(x, t)} \psi(x, t), e = -1 \quad H' = \frac{1}{2} [p + (A(t) + \nabla \chi)]^2 + (\varphi - \frac{\partial \chi}{\partial t})$$

取 $\chi = -A(t)x$ , 得到另一个规范  $H_{dE} = \frac{p^2}{2} - \varphi(x) + xE(t)$

两个规范下的波函数满足  $\psi_{pA}(t) = e^{-iA(t)x}\psi_{dE}(t)$

当 $\varphi = 0$ 时  $\vec{E} = -\frac{\partial \vec{A}}{\partial t}$ ,  $\vec{v}(t) = \vec{p} + \vec{A}(t) = \vec{p} - \frac{\vec{E}}{\omega} \sin \omega t$

Volkov function

SFA:  $i\frac{\partial}{\partial t}\psi = \frac{1}{2}(p + A(t))^2\psi$ ,  $\psi = N\varphi(t)e^{i\vec{p}\cdot\vec{r}}$

$\implies \varphi(t) = e^{-\frac{i}{2}\int^t[\vec{p}+\vec{A}(t')]\mathrm{d}t'} E(t) = E \cos \omega t, \vec{E} = -\frac{\partial \vec{A}}{\partial t} \implies \vec{A}(t) = -\frac{\vec{E}}{\omega} \sin \omega t$

$$\psi_{pA}(\vec{r}, t) = Ne^{i\vec{p}\cdot\vec{r}} e^{-i\left[\left(\frac{p^2}{2} + \frac{E^2}{4\omega^2}\right)t + \frac{\vec{p}\cdot\vec{E}}{\omega^2} - \frac{E^2}{4\omega^2} \frac{\sin 2\omega t}{2\omega}\right]}$$

$$\psi_{dE}(\vec{r}, t) = (2\pi)^{-\frac{3}{2}} e^{i\vec{p}\cdot\vec{r}} e^{-\frac{i}{2}\int^t v(t')^2 \mathrm{d}t} = Ne^{i\vec{v}\cdot\vec{r}} e^{-i\left[\left(\frac{p^2}{2} + \frac{E^2}{4\omega^2}\right)t + \frac{\vec{p}\cdot\vec{E}}{\omega^2} - \frac{E^2}{4\omega^2} \frac{\sin 2\omega t}{2\omega}\right]}$$

$$a_p(t) = -i \int_{t_i}^t \mathrm{d}t' \langle \psi_f(p) | V_L(t') | \psi_i \rangle e^{i(E_f - E_i)t'} = -i \int_{t_i}^t \mathrm{d}t' \left\langle e^{i\vec{v}(t)\cdot\vec{r}} \left| V_L(t') \right| \psi_i \right\rangle e^{-\frac{i}{2}\int_{t'}^t v(\tau)^2 \mathrm{d}\tau} e^{iI_p t'}$$

鞍点近似 作用量  $S(t, t') = -\frac{1}{2} \int_{t'}^t v(\tau)^2 \mathrm{d}\tau + I_p t'$

$$\frac{\partial S(t, t')}{\partial t'} = 0 \implies \frac{1}{2} v(t')^2 + I_p = 0, t' = t_0 \quad v(t_0) = p - \frac{E}{\omega} \sin \omega t_0 \stackrel{p=0}{=} -i\sqrt{2I_p}$$

$$t_0 = it_0'', \quad \sinh \omega t_0'' = \frac{\omega}{E} \sqrt{2I_p} = \gamma = \sqrt{\frac{I_p}{2U_p}} \quad \gamma \text{称为Keldysh参数}$$

$x(t) = X(t) + \xi(t)$ , 其中 $X(t)$ 慢,  $\xi(t)$ 快  $\langle \xi(t) \rangle = 0$  有质动力势

$$U(x) = U(X + \xi) \approx U(X) + \xi \frac{\mathrm{d}U}{\mathrm{d}X} + \dots, \quad f(x, y) = f_0 \cos \omega t = f(X + \xi, t) \approx f(X) + \xi \frac{\mathrm{d}f}{\mathrm{d}X} + \dots$$

$$m\ddot{X} + m\ddot{\xi} = -\frac{\mathrm{d}U}{\mathrm{d}X} - \xi \frac{\mathrm{d}^2 U}{\mathrm{d}X^2} + f(X, t) + \xi \frac{\mathrm{d}f}{\mathrm{d}X}, \quad m\ddot{\xi} = f(X, t) + \xi \frac{\mathrm{d}f}{\mathrm{d}X}$$

第二项快变, 可略  $\ddot{\xi} \approx \omega^2 \xi$ ,  $\xi = -\frac{f}{m\omega^2}$

$$\text{运动方程取平均 } m\langle \ddot{X} \rangle = -\frac{\mathrm{d}U}{\mathrm{d}X} + \langle \xi \frac{\mathrm{d}f}{\mathrm{d}X} \rangle = -\frac{\mathrm{d}U}{\mathrm{d}X} - \frac{1}{m\omega^2} \langle f \frac{\mathrm{d}f}{\mathrm{d}X} \rangle = -\frac{\mathrm{d}(U+U_p)}{\mathrm{d}X}$$

$$\text{其中 } U_p = \frac{1}{2m\omega^2} \langle f^2 \rangle, \text{ 对电磁场就是 } U_p = \frac{E_0^2}{4m\omega^2}$$

类比: 参变共振的摆, 振幅 $a$   $f_{eff} = -ma\omega^2 \cos \omega t \sin \varphi$

$$\text{有效势 } U_{eff} = U_p - mgl \cos \varphi = mgl[-\cos \varphi + \frac{a^2 \omega^2}{4gl} \sin^2 \varphi]$$

在 $\varphi = \pi$ 附近:  $\varphi + \varepsilon U_{eff}(\varepsilon) \approx mgl[1 - \frac{1}{2}(1 - \frac{a^2 \omega^2}{2gl})\varepsilon^2]$   $a\omega$ 较大时可以稳定平衡

在 $\psi_{dE}$ 中的 $e^{ix \sin 2\omega t}$ 项, 可利用 $e^{ix \sin \gamma} = \sum_N J_N(x) e^{iN\gamma}$ 展开, 对应等间隔的新的频率, 即缀饰态 Dressed state

$$\text{用虚时间表示的作用量 } S(0, t' = it_0'') = \frac{i}{2} \int_{t_0''}^0 v(i\tau)^2 - iI_p t_0''$$

代入 $p = 0$ 时 $v(t) = -\frac{E}{\omega} \sin \omega t_0$ 后化简得到

$$\text{Im} S(0, t' = it_0'') = \frac{E^2}{4\omega^2} \frac{\gamma \sqrt{1+\gamma^2}}{\omega} - \left(\frac{I_p}{\omega} + \frac{E^2}{4\omega^2}\right) \text{arcsinh } \gamma$$

再代入 $\gamma$ 定义以及 $U_p = \frac{E^2}{4\omega^2}$ 得到

$$\text{Im} S(0, t' = it_0'') = -\frac{I_p}{\omega} \left[(1 + \frac{1}{2\gamma^2}) \text{arcsinh } \gamma - \frac{\sqrt{1+\gamma^2}}{2\gamma}\right]$$

在 $\gamma \ll 1$ 即 $I_p \ll U_p$  (强场) 情况下  $\text{Im}S \approx -\frac{I_p}{\omega} \frac{4\gamma}{3} = -\frac{1}{3} 2^{\frac{3}{2}} I_p^{\frac{3}{2}} E^{-1}$

相应跃迁概率幅  $a_p \sim e^{\text{Im}S(0, it_0'')} \sim e^{-\frac{(2I_p)^{\frac{3}{2}}}{3E}} \sim e^{-\frac{\sqrt{me}}{e\hbar} \frac{(2I_p)^{\frac{3}{2}}}{3E}} \sim e^{-\frac{1}{E}}$

在 $\gamma \gg 1$ 即 $I_p \gg U_p$  (弱场) 情况下  $\text{Im}S \approx -\frac{I_p}{\omega} \ln 2\gamma$ ,  $a_p \sim \frac{1}{(2\gamma)^{\frac{I_p}{\omega}}} \sim [\frac{E}{2\omega} \sqrt{2I_p}]^{\frac{I_p}{\omega}} \sim E^{\frac{I_p}{\omega}}$

单位制与量纲 a.u.  $[\hbar], [m_e], [e], [4\pi\epsilon_0]$  MKS  $[M], [L], [T], [c]$

MKS到a.u.的转移矩阵  $A = \begin{pmatrix} 1 & 2 & -1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & -3 & 2 & 2 \end{pmatrix}$  反过来  $B = A^{-1} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 2 & -1 & -2 & 1 \\ 2 & -1 & -4 & 2 \\ 0 & 0 & 1 & 0 \end{pmatrix}$

即  $\begin{pmatrix} \ln[\hbar] \\ \ln[m_e] \\ \ln[e] \\ \ln[4\pi\epsilon_0] \end{pmatrix} = A \begin{pmatrix} \ln[M] \\ \ln[L] \\ \ln[T] \\ \ln[c] \end{pmatrix}$ ,  $\begin{pmatrix} \ln[M] \\ \ln[L] \\ \ln[T] \\ \ln[c] \end{pmatrix} = B \begin{pmatrix} \ln[\hbar] \\ \ln[m_e] \\ \ln[e] \\ \ln[4\pi\epsilon_0] \end{pmatrix}$

运用过来:  $(\frac{I_p^{\frac{3}{2}}}{E})_{SI} = \frac{M^{\frac{3}{2}} L^3 T^{-3}}{M L c^{-1} T^{-2}} (\frac{I_p^{\frac{3}{2}}}{E})_{a.u.} = \hbar m^{-\frac{3}{2}} (\frac{I_p^{\frac{3}{2}}}{E})_{a.u.}$

原子: 跃迁、精细结构 $l, s$ 、旋量表示、 $SO(3, 1)$ 旋量表示

应用: 超冷原子和原子钟、GPS、合成规范场、自旋极化电子束流

双原子分子: 分子振动与转动、不可约张量方法、Fano-Feshbach共振、Landau-Zener理论

多原子分子: 振动与表示、fibre,bundle与不动点定理、 $j$ -invariant 魔群月光理论

含时微扰论  $i\hbar \frac{\partial \psi}{\partial t} = \hat{H}(t)\psi$ ,  $\hat{H}(t) = H_0 + H'(t)$

$\psi(x, t) = \sum_k c_k(t) e^{-\frac{iE_k^{(0)}t}{\hbar}} \psi_k^{(0)}(x)$   $H = -\vec{\mu} \cdot \vec{E} \frac{1}{2} (e^{i\omega t} + e^{-i\omega t})$

$c_m(t) = c_m(0) - \frac{i}{\hbar} \int_0^t e^{i\omega_{mn}t} \langle \psi_m^{(0)} | \hat{H}'(t) | \psi_n^{(0)} \rangle dt$ , 代入计算得到

$c_m(t) = \delta_{mn} + \frac{i\vec{E}}{2\hbar} \cdot \langle \psi_m^{(0)} | \vec{\mu} | \psi_n^{(0)} \rangle [\frac{e^{i(\omega_{mn}+\omega)t}-1}{\omega_{mn}+\omega} + \frac{e^{i(\omega_{mn}-\omega)t}-1}{\omega_{mn}-\omega}]$

受激吸收 (SA) :  $\omega_{mn} = \omega, |m\rangle \rightarrow |n\rangle$   $\frac{dN_n}{dt} = B_{m \rightarrow n} N_m u(\nu_{mn})$

受激发射 (SE) :  $\omega_{mn} = -\omega, |n\rangle \rightarrow |m\rangle$   $\frac{dN_n}{dt} = -B_{n \rightarrow m} N_m u(\nu_{mn})$

自发辐射  $\frac{dN_n}{dt} = -A_{n \rightarrow m} N_n$

平衡时  $\frac{dN_n}{dt} = 0$ , 得到  $B_{n \rightarrow m} = B_{m \rightarrow n} = B$

以及  $\frac{N_n}{N_m} = \frac{Bu(\nu_{mn})}{Bu(\nu_{mn})+A} = e^{-\frac{h\nu_{mn}}{k_B T}}$ ,  $u(\nu_{mn}) = \frac{8\pi h \nu_{mn}^3}{c^3} \frac{1}{e^{\frac{h\nu_{mn}}{k_B T}} - 1}$

对比得到  $A = \frac{8\pi h \nu_{mn}^3}{c^3} B$

光打入分子初态 $s$ ,  $l = 1$ , 自旋 (偏振) 量子数 $q$   $q = 0 \rightarrow p_z, q = \pm 1 \rightarrow p_x, p_y$

$SO(2) : l = 1, m_l = \pm 1$   $SO(3) : l = 1, m_l = \pm 1, 0$

要求矩阵元  $\begin{pmatrix} l & 1 & l' \\ m_l & q & -m_l' \end{pmatrix} \neq 0$

$$\vec{\mu} = -e\vec{r} = -er(\hat{i} \sin \theta \cos \varphi + \hat{j} \sin \theta \sin \varphi + \hat{k} \cos \theta)$$

考察跃迁:  $\langle \vec{\mu} \rangle = \langle \psi_{nlm_l m_s} | \vec{\mu} | n'l'm'_l m'_s \rangle$ , 计算得到

$$\langle \vec{\mu} \rangle = -e \int_0^\infty r R_{nl}(r) R_{n'l'}(r) r dr \int_0^\pi \sin \theta d\theta \int_0^{2\pi} d\varphi Y_{lm}(\theta, \varphi) Y_{l'm'}(\theta, \varphi) \begin{pmatrix} \sin \theta \cos \varphi \\ \sin \theta \sin \varphi \\ \cos \theta \end{pmatrix} \delta_{m_3 m'_3}$$

记矢量部分为  $T_q^{(1)}$ ,  $q = 0, \pm 1$  选择定则  $\forall \Delta n, \Delta m_s = 0, \Delta m_l = 0, \pm 1, \Delta l = \pm 1$

非零  $\langle \mu_z \rangle$  要求  $\Delta l = \pm 1, \Delta m_l = 0$ , 非零  $\langle \mu_{x,y} \rangle$  要求  $\Delta l = \pm 1, \Delta m_l = \pm 1$

在  $\langle \psi_f | \hat{O} | \psi_i \rangle$  中,  $|\psi_i(f)\rangle$  是表示  $\Gamma^{(i,f)}$  的基函数,  $\hat{O}$  的表示为  $\Gamma^{(o)}$

在矩阵元  $\begin{pmatrix} l & 1 & l' \\ m_l & q & -m'_l \end{pmatrix}$ , 上半部分属于  $SO(3)$ , 下半部分属于  $SO(2)$

在  $\sigma^+$  光作用下,  $l = 1, m_j = -\frac{1}{2}, m_l = -1, m_s = \frac{1}{2} \rightarrow l = 1, m_j = \frac{1}{2}, m_l = 0, m_s = \frac{1}{2}$

即  $|p^- \uparrow\rangle + |p^0 \downarrow\rangle \rightarrow |p^0 \uparrow\rangle$ , 亦即自旋翻转

He原子的Quantum defect theory

$$H = H_0 + H', H' = \frac{e^2}{r_{12}}, H_0 = \left(-\frac{\hbar^2}{2m} \nabla_1^2 - \frac{2e^2}{r_1}\right) + \left(-\frac{\hbar^2}{2m} \nabla_2^2 - \frac{2e^2}{r_2}\right)$$

$$\text{零阶 } H_0 \psi_i^{(0)} = E_i^{(0)} \psi_i^{(0)}, \quad \psi_i^{(0)}(1, 2) = \psi_1(1) \psi_2(2)$$

$$\text{其中 } \psi_1(1) = \sqrt{\frac{8}{\pi a_0^3}} e^{-\frac{2r_1}{a_0}}, \psi_2(2) = \sqrt{\frac{8}{\pi a_0^3}} e^{-\frac{2r_2}{a_0}}, E_0 = -\frac{4e^2}{a_0}$$

$$\text{一阶微扰 } \langle H' \rangle = \int \psi_0^{(0)} H' \psi_0^{(0)} d\vec{r} = e^2 \int_0^\infty \psi_1^2(1) \left[ \frac{1}{r_1} - e^{-\frac{4r_1}{a_0}} \left( \frac{2}{a_0} + \frac{1}{r_1} \right) \right] d\vec{r}_1$$

其中方括号内的项在  $r_1 \rightarrow 0$  趋于0, 在  $r_1 \rightarrow \infty$  趋于  $\frac{e^2}{r_1}$

叠加上原子核构成了有效势

$$V_{eff}(r_1) = -\frac{2e^2}{r_1} + e^2 \left[ \frac{1}{r_1} - e^{-\frac{4r_1}{a_0}} \left( \frac{2}{a_0} + \frac{1}{r_1} \right) \right]$$

$$r_1 \rightarrow 0, V_{eff}(r_1) \rightarrow -\frac{2e^2}{r_1}, r_1 \rightarrow \infty, V_{eff}(r_1) \rightarrow -\frac{e^2}{r_1}$$

$$\text{精确计算得到 } E_{He} = E_0 + \langle H' \rangle = \frac{5e^2}{4a_0} = -74.8 eV$$

$\uparrow \otimes \uparrow = \text{singlet} \otimes \text{triplet}$

$$|S\rangle_{asym} = \frac{1}{\sqrt{2}}(|\uparrow\downarrow\rangle - |\downarrow\uparrow\rangle), \quad |T\rangle_{sym} = \begin{cases} |\uparrow\uparrow\rangle \\ |\downarrow\downarrow\rangle \\ \frac{1}{\sqrt{2}}(|\uparrow\downarrow\rangle + |\downarrow\uparrow\rangle) \end{cases}$$

总波函数  $\psi_{tot} = \psi_{space} \psi_{spin}$ , 其单重态和三重态为

$$\begin{cases} \psi_{singlet} = |S\rangle_{asym} \otimes (\psi_1(r_1)\psi_2(r_2) + \psi_1(r_2)\psi_2(r_1))_{sym} \\ \psi_{triplet} = |T\rangle_{sym} \otimes (\psi_1(r_1)\psi_2(r_2) - \psi_1(r_2)\psi_2(r_1))_{asym} \end{cases}$$

$$\text{x轴上的投影 } |\rightarrow\rangle = \frac{1}{\sqrt{2}}(|\uparrow\rangle + |\downarrow\rangle), |\leftarrow\rangle = \frac{1}{\sqrt{2}}(|\uparrow\rangle - |\downarrow\rangle)$$

考虑  $|T, s = 1, m_s = 0\rangle$  的态:  $|\uparrow\downarrow\rangle + |\downarrow\uparrow\rangle = (|\rightarrow\rightarrow\rangle - |\leftarrow\leftarrow\rangle)$

$$\text{旋轨耦合 } |\vec{S}| = \frac{\hbar}{2}, \vec{\mu}_e = -g_e \frac{\mu_B \vec{S}}{\hbar}, g_e = 2(1 + \frac{\alpha}{2\pi} + \cdots), \mu_B = \frac{e\hbar}{2m}$$

$$\text{电磁场 } \vec{E} = \frac{Ze}{4\pi\epsilon_0 r^2} \hat{r}, \vec{B} = -\gamma \frac{\vec{v} \times \vec{E}}{c^2}$$

$$\text{哈密顿量 } \hat{H}_i^{so} = -\vec{\mu}_e \cdot \vec{B} = -\frac{g_e \mu_B \vec{S}}{\hbar} \frac{Ze}{4\pi\epsilon_0 r} \frac{\vec{v} \times \hat{r}}{c^2} = 2\xi(r) \frac{\vec{l} \cdot \vec{s}}{\hbar^2}$$

$$\text{考虑洛伦兹变换中 } \vec{v} \rightarrow \vec{v} + d\vec{v}, \text{ 矩阵变化 } A(\vec{v} + d\vec{v}) = A(\vec{v}) + d\vec{v} \cdot \nabla_{\vec{v}} A(\vec{v})$$

$$t: \vec{x}' = A(\vec{\beta})\vec{x}, \quad t + \delta t: \vec{x}'' = A(\vec{\beta} + \delta\vec{\beta})\vec{x}$$

$$\vec{x}', \vec{x}'' \text{ 的关系: } \vec{x}'' = A_T \vec{x}', \quad A_T = A(\vec{\beta} + \delta\vec{\beta})A^{-1}(\vec{\beta}) = A(\vec{\beta} + \delta\vec{\beta})A(-\vec{\beta})$$

$$\text{取 } \vec{\beta} = (0, \beta, 0, 0), \delta\vec{\beta} = (0, \delta\beta_1, \delta\beta_2, 0), A(\vec{\beta}) = \begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

$$\text{对任意的 } \vec{\beta}, A(\vec{\beta}) = e^{\hat{\beta} \cdot \vec{K} \tanh^{-1} \beta} = \begin{pmatrix} \gamma & -\gamma\beta_1 & -\gamma\beta_2 & -\gamma\beta_3 \\ -\gamma\beta_1 & \frac{1+(\gamma-1)\beta_1^2}{\beta^2} & \frac{(\gamma-1)\beta_1\beta_2}{\beta^2} & \frac{(\gamma-1)\beta_1\beta_3}{\beta^2} \\ -\gamma\beta_2 & -\frac{(\gamma-1)\beta_1\beta_2}{\beta^2} & \frac{1+(\gamma-1)\beta_2^2}{\beta^2} & \frac{(\gamma-1)\beta_2\beta_3}{\beta^2} \\ -\gamma\beta_3 & -\frac{(\gamma-1)\beta_1\beta_3}{\beta^2} & -\frac{(\gamma-1)\beta_2\beta_3}{\beta^2} & \frac{1+(\gamma-1)\beta_3^2}{\beta^2} \end{pmatrix}$$

$$\text{由此算出 } A_T = I - \frac{\gamma-1}{\beta^2} (\vec{\beta} \times \delta\vec{\beta}) \cdot \vec{S} - (\gamma^2 \delta\vec{\beta}_{\parallel} + \gamma \vec{\beta}_{\perp}) \cdot \vec{K} = A(\Delta\beta)R(\Delta\Omega),$$

$$\text{其中Boost部分 } A(\Delta\beta) = I - \Delta\vec{\beta} \cdot \vec{K}, \text{ Rotation部分 } R(\Delta\Omega) = I - \Delta\vec{\Omega} \cdot \vec{S}, \text{ 变化量}$$

$$\begin{cases} \Delta\vec{\beta} = \gamma^2 \delta\vec{\beta}_{\parallel} + \gamma \delta\vec{\beta}_{\perp} \\ \Delta\vec{\Omega} = \frac{\gamma-1}{\beta^2} (\vec{\beta} \times \delta\vec{\beta}) = \frac{\gamma^2}{\gamma+1} (\vec{\beta} \times \delta\vec{\beta}) \approx \frac{1}{2c^2} (\vec{v} \times \delta\vec{v}) \end{cases}$$

$$\text{根据转动系数 } \left(\frac{dG}{dt}\right)_{Rot} = \left(\frac{dG}{dt}\right)_{test} + \vec{\omega}_T \times \vec{G},$$

$$\text{这里的角速度可看作 } \vec{\omega}_T = \lim_{\delta t \rightarrow 0} \frac{\Delta\vec{\Omega}}{\delta t} = \frac{\vec{v} \times \vec{a}}{2c^2}, \text{ 即Thomas进动}$$

$$\text{在量子情形中, } \frac{d\vec{S}}{dt} = \left(\frac{d\vec{S}}{dt}\right)_{test} + \vec{\omega}_T \times \vec{S}, \quad \left(\frac{d\vec{S}}{dt}\right)_{test} = \vec{\mu}_e \times \vec{B}, \text{ 从哈密顿量即可得到}$$

$$\text{即 } \frac{d\vec{S}}{dt} = \vec{S} \times \left(\frac{g\mu_B}{\hbar} \vec{B} - \vec{\omega}_T\right), \text{ 加速度 } \vec{a} = \frac{e}{m} \vec{E}, \text{ 即 } \vec{\omega}_T = -\frac{Ze^2}{4\pi\epsilon_0 r^2} \frac{-1}{2m^2 c^2} \vec{l}$$

$$\text{进而进动部分 } \hat{H}_2^{so} = \vec{S} \cdot \vec{\omega}_T = -\frac{1}{2} \left(\frac{e\hbar}{mc}\right)^2 \frac{Z}{4\pi\epsilon_0 r^3} \vec{l} \cdot \vec{s} = -\xi(r) \vec{l} \cdot \vec{s}$$

$$\text{总哈密顿量就是 } \hat{H}^{so} = \hat{H}_1^{so} + \hat{H}_2^{so} = \xi(r) \vec{l} \cdot \vec{s}, \quad \xi(r) = O(\alpha^2)$$

$$\text{考虑飞机圆周运动 } S: \text{飞机系 } S': \text{Lab frame(LF)}$$

$$\text{考虑短时间: } \parallel \text{方向运动 } L, \perp \text{方向运动 } W, S \text{ 中 } \varphi = \frac{W}{L}, S' \text{ 中 } \varphi' = \frac{W}{L} = \gamma\varphi$$

$$\text{加和就是 } \sum \varphi' = 2\pi\gamma, \text{ 多出来的部分就是进动角 } \Delta\theta = 2\pi(1 - \gamma)$$

$$\text{进动角速度和角速度之比 } \frac{\omega_T}{\omega} = \frac{\Delta\theta}{2\pi} = 1 - \gamma = -\frac{1}{\sqrt{1-\beta^2}} + 1 \approx -\frac{1}{2}\beta^2$$

$$\text{由此得到 } \omega_T = -\frac{1}{2}\beta^2\Omega = -\frac{1}{2c^2} \vec{v} \cdot \vec{a} = \frac{1}{2c^2} \vec{a} \times \vec{v}$$

$$\text{Rotation算符 } S \text{ 和 Boost算符 } K$$

$$\text{转动: } S_1 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{pmatrix}, \quad S_2 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{pmatrix}, \quad S_3 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\text{分别为绕 } x, y, z \text{ 轴, 如 } e^{\theta S_1} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \cos \theta & \sin \theta \\ 0 & 0 & -\sin \theta & \cos \theta \end{pmatrix}$$

$$\text{Boost: } K_1 = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad K_2 = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad K_3 = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

$$\text{分别为 } x, y, z \text{ 轴上的boost, 如 } e^{-\zeta K_1} = \begin{pmatrix} \cosh \zeta & -\sinh \zeta & 0 & 0 \\ -\sinh \zeta & \cosh \zeta & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\text{算符满足对易关系 } [S_i, S_j] = \varepsilon_{ijk} S_k, \quad [K_i, K_j] = -\varepsilon_{ijk} S_k, \quad [S_i, K_j] = \varepsilon_{ijk} K_k$$

Boost代数不封闭

$$\text{由此可用Boost代数进行前面计算, 一般洛伦兹矩阵 } A(\hat{\beta}) = e^{\hat{\beta} \cdot K \varphi}, \varphi = \tanh^{-1} \beta$$

$$\text{相应进动部分 } A_T = A(\beta + \delta\beta)A(-\beta) = A(\hat{\beta} + \delta\hat{\beta}, \varphi + \delta\varphi)A(\hat{\beta}, -\varphi) = e^{(\hat{\beta} + \delta\hat{\beta}) \cdot K(\varphi + \delta\varphi)} e^{-\hat{\beta} \cdot K \varphi}$$

$$\text{利用CBH等式 } e^A e^B = e^{A+B+\frac{1}{2}[A,B]+\frac{1}{12}([A,[A,B]]+[B,[B,A]])} \text{ 可以化简得到}$$

$$A_T = 1 + \hat{\beta} \cdot K \delta\varphi + \delta\hat{\beta} \cdot K \varphi - \frac{1}{2} [\delta\hat{\beta} \cdot K, \beta \cdot K] \varphi^2$$

$$\text{利用 } [K_r, K_s] = -\varepsilon_{rst} S_t \text{ 有 } [\delta\hat{\beta} \cdot K, \hat{\beta} \cdot \hat{K}] = -(\delta\hat{\beta} \times \beta) \cdot S$$

$$\text{进而 } A_T = 1 + (\hat{\beta} \cdot K) \delta\varphi + (\delta\hat{\beta} \cdot K) \varphi - \frac{1}{2} \varphi^2 (\delta\hat{\beta} \times \beta) \cdot S$$

$$\text{与 } \vec{S} \text{ 相关的代表rotation, 其转角为 } \Omega_T \Delta t = \frac{1}{2} \varphi^2 (\delta\hat{\beta} \times \beta) = \frac{1}{2} (\tanh^{-1} \beta)^2 \frac{\delta \vec{v} \times \vec{v}}{c^2}$$

$$\text{因此角速度 } \Omega_T = \frac{1}{2} (\tanh^{-1} \beta)^2 \frac{\vec{a} \times \vec{v}}{c}$$

并旋量->并矢  $SO(3)$  旋量表示-> $SO(3, 1)$  旋量表示

$$O(2) \text{ rotation: } R = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}, \det |R| = 1 \quad \tau = \begin{pmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{pmatrix}, \det |\tau| = 1$$

作  $\mathbb{R}^3 \rightarrow \mathbb{R} \times \mathbb{C}$  的映射:  $(x, y, z) \rightarrow (z, x + iy)$ , 并取旋量

$$\tau = x\sigma_x + y\sigma_y + z\sigma_z = \begin{pmatrix} z & x - iy \\ x + iy & -z \end{pmatrix}$$

$$\text{则 } \hat{e}_x \rightarrow \sigma_x, \hat{e}_y \rightarrow \sigma_y, \hat{e}_z \rightarrow \sigma_z$$

$$\text{旋量 } \tau \text{ 把旋量 } a = a_x \sigma_x + a_y \sigma_y + a_z \sigma_z \text{ 沿着与 } (x, y, z) \text{ 垂直的面反射至 } b = b_x \sigma_x + b_y \sigma_y + b_z \sigma_z$$

$$\text{给定 } \hat{n}, \text{ 矢量可写为平行垂直分解 } a = (a \cdot \hat{n}) \hat{n} + (a - (a \cdot \hat{n}) \hat{n}) = a_{\parallel} + a_{\perp},$$

$$\text{沿与 } \hat{n} \text{ 垂直的面反射为 } a' = -(a \cdot \hat{n}) \hat{n} + (a - (a \cdot \hat{n}) \hat{n}) = a - 2(a \cdot \hat{n}) \hat{n} \quad (\text{Euler-Rodrigues公式})$$

$$\text{用 } \sigma \text{ 作用有 } \sigma \cdot a' = \sigma \cdot a - 2(a \cdot n)(\sigma \cdot n)$$

利用 $(\sigma \cdot a)(\sigma \cdot b) = a \cdot b + i\sigma \cdot (a \times b)$ 有 $a \cdot b = \frac{1}{2}\{(\sigma \cdot a), (\sigma \cdot b)\}$

进而 $\sigma \cdot a' = -(\sigma \cdot n)(\sigma \cdot a)(\sigma \cdot n)$ , 即在垂直 $\vec{n}$ 面的反射作用

连续两次反射:  $\alpha, \beta$ , 记 $R = (\sigma \cdot \beta)(\sigma \cdot \alpha)$ , 则 $\sigma a' = R(\sigma \cdot a)R$ ,  $R$ 为Euler-Rodrigues矩阵

$R$ 的计算: 设 $\alpha, \beta$ 夹角 $2\varphi$ 且 $\hat{n}$ 垂直 $\alpha, \beta$ , 则

$$R = (\alpha \cdot \beta) - i(\alpha \times \beta) \cdot \sigma = \cos \frac{\varphi}{2} - i \sin \frac{\varphi}{2} \hat{n} \cdot \sigma = e^{i \frac{\varphi}{2} \hat{n} \cdot \sigma}, \text{ 且 } R(4\pi, \hat{n}) = 1, R(2\pi, \hat{n}) = -1$$

$$SO(3): a \rightarrow a' = \tilde{R}a, \quad SU(2): \sigma \cdot a \rightarrow \sigma \cdot a' = R(\sigma \cdot a)R$$

$$SU(2) \text{生成元: } X_{12} = -\frac{i}{2}\sigma_1\sigma_2, X_{23} = -\frac{i}{2}\sigma_2\sigma_3, X_{31} = -\frac{i}{2}\sigma_3\sigma_1$$

考虑 $SO(3, 1) \rightarrow SL(2, \mathbb{C})$

从 $\mathbb{R}^{3,1} \rightarrow (\mathbb{R}^2 \times \mathbb{C}): (t, x, y, z) \rightarrow (t+z, t-z, x+iy)$ 即光锥坐标

$$\text{取 } Z = \begin{pmatrix} t+z & x-iy \\ x+iy & t-z \end{pmatrix}, \text{ 令 } K^i = (\pm)\sigma_i, S^i = i\sigma_i$$

$$\text{对易关系 } [K_i, K_j] = 2\varepsilon_{ijk}S_k, [S_i, S_j] = -2\varepsilon_{ijk}S_k, [S_i, K_j] = -2\varepsilon_{ijk}K_k, [K_i, S_j] = -2\varepsilon_{ijk}K_k$$

$$R^{1,1} \times \mathbb{C} \text{空间的旋量基: } e, \sigma_1, \sigma_2, \sigma_3 \quad Z = te + x\sigma_1 + y\sigma_2 + z\sigma_3$$

$$\text{Rotation } U_\theta = \begin{pmatrix} e^{-i\theta} & 0 \\ 0 & e^{i\theta} \end{pmatrix}, \quad U_\theta Z U_\theta^\dagger = \begin{pmatrix} t+z & e^{-2i\theta}(x-iy) \\ e^{2i\theta}(x+iy) & t-z \end{pmatrix}, \text{ 即} \\ x+iy \rightarrow e^{2i\theta}(x+iy)$$

$$\text{Boost } M_r = \begin{pmatrix} r & 0 \\ 0 & r^{-1} \end{pmatrix}, \quad M_r Z M_r^\dagger = \begin{pmatrix} r^2(t+z) & x-iy \\ x+iy & r^{-2}(t-z) \end{pmatrix}$$

$$\text{相当于 } \begin{cases} t' = \frac{1}{2}(r^2 + r^{-2})t + \frac{1}{2}(r^2 - r^{-2})z \\ z' = \frac{1}{2}(r^2 - r^{-2})t + \frac{1}{2}(r^2 + r^{-2})z \end{cases}$$

$$\text{令 } r = e^{\frac{u}{z}}, \text{ 则相当于 } \begin{cases} t' = \cosh u t + \sinh u z \\ z' = \sinh u t + \cosh u z \end{cases} \text{ 也可由 } e^{u\sigma_x} = \begin{pmatrix} \cosh u & \sinh u \\ \sinh u & \cosh u \end{pmatrix} \text{ 得到}$$

$$\text{若用 } J_i = -\frac{i}{2}S_i, K_i = -\frac{i}{2}K_i \text{ (前面的 } K), N_i^\pm = \frac{1}{2}(J_i \pm iK_i)$$

$$\text{对易关系 } [N_i^-, N_j^-] = i\varepsilon_{ijk}N_k^-, [N_i^+, N_j^+] = i\varepsilon_{ijk}N_k^+, [N_i^+, N_j^-] = 0$$

即两部分对易关系独立, 亦即 $SO(3, 1) \sim SU(2)_L \otimes SU(2)_R$ , 分解为Weyl spinor

$$H = \sigma \cdot r = \begin{pmatrix} z & x-iy \\ x+iy & -z \end{pmatrix} = \begin{pmatrix} \xi_1 & \xi_2^* \\ \xi_2 & -\xi_1 \end{pmatrix} \quad \text{2D复空间 } \xi = \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix}$$

$$\text{令 } S = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = S^*, \text{ 构造对偶旋量 } \chi = S\xi^* = \begin{pmatrix} -\xi_2^* \\ \xi_1^* \end{pmatrix}$$

$$\text{酉变换 } U = \begin{pmatrix} a & b \\ -b^* & a^* \end{pmatrix}, \text{ 其满足 } U = SU^*S^{-1} \implies US = SU^*$$

$$\text{在变换 } \xi \rightarrow U\xi^* \text{ 下, } \chi \rightarrow (SU^*S^{-1})S\xi^* = U\chi$$

$$\text{定义 } h = \xi\chi^\dagger = \begin{pmatrix} -\xi_1\xi_2 & \xi_1^2 \\ -\xi_2^2 & \xi_1\xi_2 \end{pmatrix}, \text{ 则 } h \rightarrow UhU^\dagger$$

$$\text{令 } h = H \text{ 得 } \begin{cases} x = \frac{1}{2}(\xi_1^2 - \xi_2^2) \\ y = \frac{i}{2}(\xi_1^2 + \xi_2^2) \\ z = -\xi_1 \xi_2 \end{cases}, \quad \begin{cases} \xi_1 = \pm \sqrt{x - iy} \\ \xi_2 = \pm \sqrt{-x - iy} \end{cases}$$

$\begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix}$  为旋量的2分量形式

$SO(3, 1) = SU(2)_A \otimes SU(2)_B$   $\varphi_A, \varphi_B$  分别为  $SU(2)_A, SU(2)_B$  的(Weyl)旋量

$\varphi_A$  在  $SU(2)_A$  下变换, 在  $SU(2)_B$  作用下不变,  $\varphi_B$  不同

$$\begin{cases} \varphi_A \rightarrow e^{i\alpha_A N^+} \varphi_A; & \varphi_A \rightarrow e^{i\alpha_B N^-} \varphi_A = \varphi_A \\ \varphi_B \rightarrow e^{i\alpha_A N^+} \varphi_B = \varphi_B; & \varphi_B \rightarrow e^{i\alpha_B N^-} \varphi_B \end{cases}$$

构造 Lorentz  $SO(3, 1)$  的 Dirac 旋量

$$\begin{cases} e^{i\alpha_A N^+} \varphi_B = \sum_{n=0}^{\infty} \frac{1}{n!} (i\alpha_A N^+)^n \varphi_B = \varphi_B \implies N_i^+ \varphi_B = 0 \implies S_i \varphi_B = -iK_i \varphi_B \\ e^{i\alpha_B N^-} \varphi_A = \sum_{n=0}^{\infty} \frac{1}{n!} (i\alpha_B N^-)^n \varphi_A = \varphi_A \implies N_i^- \varphi_A = 0 \implies S_i \varphi_A = iK_i \varphi_A \end{cases}$$

$$\varphi_A: J_i = -\frac{i}{2} S_i = \frac{\sigma_i}{2}, \quad K_i = -iJ_i = -i\frac{\sigma_i}{2}$$

$$\varphi_B: J_i = \frac{\sigma_i}{2}, \quad K_i = iJ_i = i\frac{\sigma_i}{2}$$

$$\text{Lorentz 变换: } \varphi_A \rightarrow e^{i(\theta^i J_i + \varphi^i K_i)} \varphi_A = e^{\frac{i}{2}(\sigma \cdot \theta - i\sigma \cdot \varphi)} \varphi_A$$

$$\text{即 } \begin{cases} \varphi_A \rightarrow e^{\frac{i}{2}\sigma \cdot (\theta - i\varphi)} \varphi_A \\ \varphi_A^\dagger \rightarrow \varphi_A^\dagger e^{-\frac{i}{2}\sigma \cdot (\theta + i\varphi)} \end{cases}, \quad \begin{cases} \varphi_B \rightarrow e^{\frac{i}{2}\sigma \cdot (\theta + i\varphi)} \varphi_B \\ \varphi_B^\dagger \rightarrow \varphi_B^\dagger e^{-\frac{i}{2}\sigma \cdot (\theta - i\varphi)} \end{cases}$$

一个静止的例子 boost 到动量  $p$  的态  $\varphi_{A,B}(0) \rightarrow \varphi_{A,B}(p)$

沿着  $\hat{p}$  作  $\varphi$  的 boost 变换  $\varphi = \varphi \hat{p}$

$$\begin{aligned} \varphi_A(p) &= e^{\sigma \cdot \frac{\varphi}{2}} \varphi_A(0) \\ &= \left[ \sum_{n=0}^{\infty} \frac{1}{(2n)!} \left( \sigma \cdot \frac{\varphi}{2} \right)^{2n} + \sum_{n=0}^{\infty} \frac{1}{(2n+1)!} \left( \sigma \cdot \frac{\varphi}{2} \right)^{2n+1} \right] \varphi_A(0) \\ &= \left[ \sum_{n=0}^{\infty} \frac{1}{(2n)!} \left( \frac{\varphi}{2} \right)^n + \sigma \cdot \hat{p} \sum_{n=0}^{\infty} \frac{1}{(2n+1)!} \left( \frac{\varphi}{2} \right)^{2n+1} \right] \varphi_A(0) \\ &= \left( \cosh \frac{\varphi}{2} + \sigma \cdot \hat{p} \sinh \frac{\varphi}{2} \right) \varphi_A(0) \end{aligned}$$

代入  $\cosh \varphi = \gamma = \frac{E}{m}$ ,  $|p| = \frac{p}{m\sqrt{\gamma^2 - 1}}$  可得

$$\varphi_A = \frac{m(\gamma + 1) + \sigma \cdot p}{\sqrt{2m^2(\gamma + 1)}} \varphi_A(0) = \frac{E + m + \sigma \cdot p}{\sqrt{2m(E + m)}} \varphi_A(0)$$

同理

$$\varphi_B = \frac{E + m - \sigma \cdot p}{\sqrt{2m(E + m)}} \varphi_B(0)$$

$$\text{静止系下 } p = 0, \varphi = 0, \begin{cases} \varphi_A \rightarrow e^{\frac{i}{2}\sigma \cdot \theta} \varphi_A \\ \varphi_B = e^{\frac{i}{2}\sigma \cdot \theta} \varphi_B \end{cases}$$

$$\text{若 } \varphi_A(0) = \varphi_B(0), \text{ 则 } \varphi_A(p) = \frac{E+m+\sigma \cdot p}{E+m-\sigma \cdot p} \varphi_B(p), \text{ 即 } \begin{cases} \varphi_A(p) = \frac{E+\sigma \cdot p}{m} \varphi_B(p) \\ \varphi_B(p) = \frac{E-\sigma \cdot p}{m} \varphi_A(p) \end{cases}$$



亦即

$$\begin{pmatrix} -m & E + \sigma \cdot p \\ E - \sigma \cdot p & -m \end{pmatrix} \begin{pmatrix} \varphi_A(p) \\ \varphi_B(p) \end{pmatrix} = 0$$

定义Dirac旋量(spinor)  $\psi = \begin{pmatrix} \varphi_A \\ \varphi_B \end{pmatrix}$  以及矩阵  $\gamma^0 = \begin{pmatrix} 0 & I \\ I & 0 \end{pmatrix}, \gamma^i = \begin{pmatrix} 0 & -\sigma_i \\ \sigma_i & 0 \end{pmatrix}$

得到  $(\gamma^\mu p_\mu - m)\psi(p) = 0$

$E \sim i \frac{\partial}{\partial t}, p \sim -i \nabla$ , 即有Dirac方程  $(i\partial - m)\psi = 0, \quad \partial = \gamma^\mu \partial_\mu$

$A^\mu, A_\mu$  分别为逆变, 协变  $x^\mu = (t, \vec{x}) \quad (x_\mu) = \langle x, e_\mu \rangle = x^\nu g_{\nu\mu} = (t, -\vec{x})$   
 $\partial^\mu = (\partial_0, -\nabla), \partial_\mu = (\partial_0, \nabla)$

逆变  $A^\mu \rightarrow A'^\mu = \frac{\partial x'^\mu}{\partial x^\nu} A^\nu$  协变  $B_\mu \rightarrow B'_\mu = \frac{\partial x^\nu}{\partial x'^\mu} B_\mu$

引入  $\alpha = \gamma^0 \gamma^i = \begin{pmatrix} \sigma_i & 0 \\ 0 & -\sigma_i \end{pmatrix}, \beta = \gamma^0 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix},$

哈密顿量  $\hat{H} = c\alpha \cdot p + \beta mc^2, p=0$  时  $\hat{H} = \beta mc^2$

Weyl representation:  $\alpha^W = \begin{pmatrix} \sigma & 0 \\ 0 & -\sigma \end{pmatrix}, \beta^W = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

Dirac-Pauli representation  $\alpha^{D-P} = \begin{pmatrix} 0 & \sigma \\ \sigma & 0 \end{pmatrix}, \beta^{D-P} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

转换矩阵  $W = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}, \alpha_i^W = W^T \alpha_i^{D-P} W, \beta^W = W^T \beta^{D-P} W$

$i\hbar \frac{\partial}{\partial t} \psi = \hat{H} \psi, \hat{H} = c\alpha \cdot p + \beta mc^2$

$\dot{x} = c\alpha_x$ , 即  $\hat{v} = c\hat{\alpha}$ ,  $v = c$ , 但  $\langle v \rangle_H = \frac{c^2 p}{E} < c$

模式展开  $\psi(r, t) = \frac{1}{\hbar^{\frac{3}{2}}} \int [C^+(p)e^{-i\omega t} + C^-(p)e^{i\omega t}] e^{\frac{ip \cdot r}{\hbar}} d^3 p, \omega = \frac{E}{\hbar}, E = \sqrt{c^2 p^2 + m^2 c^4}$

其中  $C^+(p) = a_1 u_1 + a_2 u_2, \quad C^-(p) = a_3 u_3 + a_4 u_4$

$$u_1 = \begin{pmatrix} 1 \\ 0 \\ kp_3 \\ kp_+ \end{pmatrix}, \quad u_2 = \begin{pmatrix} 0 \\ 1 \\ kp_- \\ -kp_3 \end{pmatrix}, \quad u_3 = \begin{pmatrix} -kp_3 \\ -kp_+ \\ 1 \\ 0 \end{pmatrix}, \quad u_4 = \begin{pmatrix} -kp_- \\ kp_3 \\ 0 \\ 1 \end{pmatrix}$$

其中  $k = \frac{c}{E+mc^2}, p_\pm = p_1 \pm ip_2$

平均速度  $\langle v \rangle = \langle \dot{r} \rangle = c \langle \alpha \rangle = c \int (C^{+*} \alpha C^+ + C^{-*} \alpha C^-) d^3 p + 2c \int \text{Re}(C^{+*} \alpha C^-) e^{2i\omega t} d^3 p$

第二项代表量子拍 (quantum beating)。利用  $C^{\pm*} \alpha C^\pm = \pm \frac{cp}{E} C^{\pm*} C^\pm$  可得

$$\langle \dot{r} \rangle = v + 2c \int K(p) \sin(2\omega t + \varphi(p)) d^3 p$$

其中  $v = c \int \frac{p}{mc} (1 + (\frac{p}{mc})^2)^{-\frac{1}{2}} (C^{+*} C^+ + C^{-*} C^-) d^3 p,$

$K(p) = |C^{-*} \alpha C^+|, \varphi(p) = \tan^{-1} \frac{\text{Re}(C^{-*} \alpha C^+)}{\text{Im}(C^{-*} \alpha C^+)}$

进而

$$\langle r \rangle = r^0 + vt - \bar{\lambda} \int K(p) \frac{1}{\sqrt{1 + (\frac{p}{mc})^2}} \cos(2\omega t + \varphi(p)) d^3p, \quad \bar{\lambda} = \frac{\hbar}{mc} \sim 2pm$$

$$t = 0 \text{ 时, } \psi(r, 0) = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} f\left(\frac{r}{r_0}\right), \quad f\left(\frac{r}{r_0}\right) \left(\frac{2}{\pi r_0^3}\right)^{\frac{3}{2}} e^{-\frac{r^2}{r_0^2}}$$

$$\text{而 } C^+(p) = \frac{f(\frac{p}{\eta})}{1 + k^2 p^2} \begin{pmatrix} 1 \\ 0 \\ kp_3 \\ kp_+ \end{pmatrix}, \quad C^-(p) = \frac{f(\frac{p}{\eta})}{1 + k^2 p^2} \begin{pmatrix} k^2 p^2 \\ 0 \\ -kp_3 \\ -kp_+ \end{pmatrix}$$

$$\text{利用 } \psi(r, t = 0) \sim \int [C^+(p) + C^-(p)] e^{\frac{ip \cdot r}{\hbar}} d^3p \text{ 可知 } \psi(p, t = 0) \propto f\left(\frac{p}{\eta}\right) \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$t > 0, \quad \psi(r, t) = \frac{1}{\hbar^{\frac{3}{2}}} \left[ \begin{pmatrix} 1 \\ 0 \\ kp_3 \\ kp_+ \end{pmatrix} e^{-i\omega t} + \begin{pmatrix} k^2 p^2 \\ 0 \\ -kp_3 \\ -kp_+ \end{pmatrix} e^{i\omega t} \right] \frac{f(\frac{p}{\eta})}{1 + k^2 p^2} e^{\frac{ip \cdot r}{\hbar}} d^3p$$

$$\text{利用 } r_0 > \bar{\lambda}, p \ll mc \text{ 可近似 } k \approx \frac{1}{2mc},$$

$$\psi(r, t) \text{ 的半经典轨道: 近似有 } K_1^{\alpha_1}(p) \approx \frac{f^2(\frac{p}{\eta})}{2mc} \sqrt{p_1^2 + p_2^2}, \quad K_2^{\alpha_2}(p) = K_1^{\alpha_1}(p), \quad K_3^{\alpha_3} = \frac{f^2(\frac{p}{\eta})}{2mc} p_3$$

$$\text{相应 } \tan \varphi_i = \frac{\text{Re}(C^{-*} \alpha_i C^+)}{\text{Im}(C^{-*} \alpha_i C^+)}, \text{ 即 } \begin{cases} \tan \varphi_1 = -\frac{p_1}{p_2} \\ \tan \varphi_2 = \frac{p_2}{p_1} \\ \tan \varphi_3 = \infty \end{cases}, \text{ 即 } \begin{cases} \varphi_1 = \varphi + \pi \\ \varphi_2 = \varphi \\ \varphi_3 = \frac{\pi}{2} \end{cases}$$

$$\text{取球坐标 } \begin{cases} p_1 = p \sin \theta \cos \varphi \\ p_2 = p \sin \theta \sin \varphi, \text{ 进而 } K_1 = K_2 = \frac{f^2(\frac{p}{\eta})}{2mc} p \sin \theta, K_3 = \frac{f^2(\frac{p}{\eta})}{2mc} p \cos \theta \\ p_3 = p \cos \theta \end{cases}$$

$\langle x_i \rangle$ ——电子颤动(jitter)的半经典轨道

$$\text{积分得到 } \langle x_1 \rangle = -I \int_0^{2\pi} \bar{\lambda} \sin(2\omega t + \varphi) d\varphi, \quad I = \frac{\bar{\lambda}}{32r_0} \left(\frac{2}{\pi}\right)^{\frac{3}{2}},$$

$$\text{里面关于 } \varphi \text{ 的轨道 } \langle x_1 \rangle_{\varphi} = -I \bar{\lambda} \sin(2\omega t + \varphi), \text{ 同理 } \langle x_2 \rangle_{\varphi} = -I \bar{\lambda} \cos(2\omega t + \varphi)$$

$$\text{磁矩 } \mu = \frac{1}{2c} \langle r \times j \rangle = \frac{e}{2c} \langle r \times \dot{r} \rangle,$$

$$\text{其中 } \langle r \times \dot{r} \rangle = c \langle r \times \alpha \rangle \rightarrow i\hbar c \langle \nabla_p \times \alpha \rangle, \text{ 经过计算得到}$$

$$\langle r \times \dot{r} \rangle_1 = \langle r \times \dot{r} \rangle_2 = 0, \quad \langle r \times \dot{r} \rangle_3 = \frac{\hbar}{m} (1 - \cos 2\omega t),$$

$$\text{从而 } \mu_1 = \mu_2 = 0, \quad \mu_3 = \frac{e\hbar}{2mc} (1 - \cos 2\omega t)$$

考虑绕核运动将会有修正效应, 设电子速度 $\vec{v}$ , 模型化为垂直原子平面的圆盘, 进动角 $\varphi$ , 圆周运动角 $\psi$

$$\text{实验室系(LF)下质点速度 } \begin{cases} u_x = u_0 \cos \psi \cos \varphi - v \\ u_y = u_0 \cos \psi \sin \varphi \\ u_z = -u_0 \sin \psi \end{cases}, \text{ 合起来 } u^2 = u_0^2 + v^2 - 2vu_0 \cos \psi \cos \varphi$$

$$\text{即 } \gamma = \frac{1}{\sqrt{1-\frac{v^2}{c^2}}} \approx 1 + \frac{u_0^2+v^2}{2c} - \frac{vu_0}{c^2} \cos \psi \cos \varphi$$

$$\text{实验系(LF)为 } S', \text{ 自旋系(SF)为 } S, \text{ 关联 } \begin{cases} x' = \gamma(x - vt) \\ t' = \gamma(t - \frac{vx}{c^2}) \\ y' = y \\ z' = z \end{cases},$$

$$\text{在LF, } t' = 0 \implies \text{SF, } t = \frac{vx}{c^2}, x = \frac{c^2}{v}t \text{ 且 } x = r \sin(\omega t + \psi) \cos \varphi$$

$$\text{按 } \omega t \text{ 展开: } x = r \cos \varphi [\sin \psi + (\omega t) \cos \psi + O(\omega t)^2]$$

$$\text{代入 } x = \frac{c^2}{v}t \text{ 得到 } t = \frac{vr}{c^2} \cos \varphi \sin \psi$$

$$\text{从而 } z'(t' = 0) = z(t' = 0) = z(t = \frac{vr}{c^2} \cos \varphi \sin \psi) = r \cos [\omega(\frac{vr}{c^2} \cos \varphi \sin \psi) + \psi]$$

$$\text{近似为 } z'(t' = 0) = r \cos \psi - \frac{vr^2}{c^2} \omega \cos \varphi \sin^2 \psi$$

$$\text{质心位置 } \gamma_{dm} = \gamma(x', y', z')_{dm}$$

$$z'_{CM} = \langle \gamma z' \rangle_\psi, \text{ 近似计算得到 } \gamma z' = -r \cos^2 \psi \cos \varphi \frac{u_0 v}{c^2} - \frac{vr^2 \omega}{c^2} \cos \varphi \sin^2 \psi$$

$$\text{从而 } z'_{CM} = -\frac{vr^2 \omega}{c^2} \cos \varphi$$

$$\text{自旋 } S = |S| = |r \times p| = Mr^2 \omega, \quad r^2 \omega = \frac{S}{M}, \text{ 即 } z'_{CM} = -\frac{vS}{Mc^2} \cos \varphi$$

$$\text{力 } F = -M \frac{v^2}{R}, \text{ 自旋导数 } \frac{dS}{dt} = (z \times F)_\perp = Fz \cos \varphi = \frac{v^3 S}{Rc} \cos^2 \varphi$$

$$\text{进动角速度 } \frac{d\varphi}{dt} = \frac{1}{S} \frac{dS}{dt} = \frac{v^3}{Rc^2} \cos^2 \varphi$$

$$\text{令 } \Omega = \frac{v}{R}, \beta = \frac{v}{c} \text{ 则 } \frac{d\varphi}{dt} = \Omega \beta^2 \cos^2 \varphi, \text{ 均值 } \langle \frac{d\varphi}{dt} \rangle_\varphi = \frac{1}{2} \Omega \beta^2 = \Omega_T$$

$$\text{加速度 } a = -v\Omega, \text{ 故 } \Omega_T = -\frac{1}{2} \frac{a \cdot v}{c^2}, \frac{\Omega_T}{\Omega} = \frac{1}{2} \beta^2,$$

$$\text{考虑多电子原子, } \hat{H} = \sum_i (-\frac{\hbar^2}{2m} \nabla_i^2 - \frac{Ze^2}{r_i}) + \sum_{ij} \frac{e^2}{r_{ij}} + \sum_i \zeta(r_i) \hat{l}_i \cdot \hat{s}_i$$

$$\zeta(r) \propto \frac{1}{2} \frac{Z\alpha^2}{r^3}, Z \uparrow, r \downarrow \implies \zeta \uparrow, \text{ 自旋轨道耦合 } E_{SOC} \uparrow$$

$$\text{例: } {}^3D_1, |L=2, S=1, J=1, M_J=0\rangle$$

$$\text{最高权态出发 } |L=2, S=1, J=3, M_J=3\rangle = |L=2, S=1, M_L=2, M_S=1\rangle$$

$$\hat{J}_- |2133\rangle (LSJM_J) = (\hat{L}_- + \hat{S}_-) |2121\rangle (LSM_L M_S)$$

$$\text{利用 } J_\pm |JM_J\rangle = \sqrt{J(J+1) - M_J(M_J \pm 1)} |JM_J \pm 1\rangle \text{ 得}$$

$$|2132\rangle = \frac{2}{\sqrt{6}} |2111\rangle + \frac{1}{\sqrt{3}} |2120\rangle$$

$$J \text{ 降1: } |2122\rangle = a |2111\rangle + b |2120\rangle$$

$$\text{要求 } \langle 2122 | 2132 \rangle = 0 \text{ 与归一 } \implies |2122\rangle = -\frac{1}{\sqrt{3}} |2111\rangle + \sqrt{\frac{2}{3}} |2120\rangle$$

$$\text{同理 } |2111\rangle = -\frac{1}{\sqrt{10}} |2101\rangle + \sqrt{\frac{3}{10}} |2110\rangle - \sqrt{\frac{3}{5}} |212-1\rangle$$

$$|2110\rangle = \sqrt{\frac{3}{10}} |21-11\rangle - \sqrt{\frac{2}{5}} |2100\rangle + \sqrt{\frac{3}{10}} |211-1\rangle$$

$$\text{系数记为C-G系数 } \begin{pmatrix} 2 & 1 & 1 \\ -1 & 1 & 0 \end{pmatrix} \text{ 等, 即 } \begin{pmatrix} j_1 & j_2 & J \\ m_1 & m_2 & M \end{pmatrix}$$

亦即 $|lsjm_j\rangle=\sum_{m_lm_s}|lsm_lm_s\rangle\langle lsm_lm_s|lsjm_j\rangle$ ,  $\langle lsm_lm_s|lsjm_j\rangle$ 为C-G系数

3Γ Coefficient (Fano V Coefficient)

$$\Gamma_1\otimes\Gamma_2=\sum_ic_i\Gamma_i\quad|\Gamma_1,\Gamma_2,\Gamma,M\rangle=\sum_{M_1M_2}\langle\Gamma_1M_1\Gamma_2M_2|\Gamma M\rangle\,|\Gamma_1M_1\rangle\,|\Gamma_2M_2\rangle$$

归一关系  $\sum_{M_1M_2}\langle\Gamma_1M_1\Gamma_2M_2|\Gamma M\rangle\,\langle\Gamma_1M_1\Gamma_2M_2|\Gamma'M'\rangle=\delta_{\Gamma\Gamma'}\delta_{M'M}$

交换关系  $\begin{pmatrix}\Gamma_2&\Gamma_1&\Gamma_3\\M_2&M_1&M_3\end{pmatrix}=(-)^{\Gamma_1+\Gamma_2+\Gamma_3}\begin{pmatrix}\Gamma_1&\Gamma_2&\Gamma_3\\M_1&M_2&M_3\end{pmatrix}$

Wigner-Eckart定理  $\langle\Gamma_1M_1|\hat{O}_{M_2}^{\Gamma_2}|\Gamma_3M_3\rangle\propto\begin{pmatrix}\Gamma_1&\Gamma_2&\Gamma_3\\M_1&M_2&M_3\end{pmatrix}\langle\Gamma_1||O^{\Gamma_2}||\Gamma_3\rangle$

自旋极化的电子源

$$\psi_K^{p-e,k_e}=\sum_{p^\alpha,R_N^\alpha}c_{p\alpha}(R_N^\alpha)\varphi_{p^\alpha}^{AO}(r_e-R_N^\alpha)\sim\sum_{p^\alpha,R_N^\alpha}e^{iK\cdot R_N^\alpha}\tilde{c}_p(R_N^\alpha)\varphi_{p^\alpha}^{AO}(r_\alpha-R_N^\alpha)$$

$K=0$ 时  $\varphi_0^{p-e,k_e}(r_e)=\sum_{p^\alpha,R_N^\alpha}\tilde{c}_p(R_N^\alpha)\varphi_{p^\alpha}^{AO}(r_e-R_N^\alpha)$

苯分子  $C_6$ 对称群  $|\psi_k\rangle\sim\frac{1}{\sqrt{n}}(|v_1\rangle+e^{i\frac{k}{n}2\pi}|v_2\rangle+\cdots e^{i\frac{k}{n}(n-1)2\pi}|v_n\rangle)$

$$n=6:H=\begin{pmatrix}\alpha&\beta&0&0&0&\beta\\ \beta&\alpha&\beta&0&0&0\\ 0&\beta&\alpha&\beta&0&0\\ 0&0&\beta&\alpha&\beta&0\\ 0&0&0&\beta&\alpha&\beta\\ \beta&0&0&0&\beta&\alpha\end{pmatrix}\varepsilon_k=\alpha+2\beta\cos\frac{\pi}{3}k\beta<0$$

$\alpha+2\beta$ 成键  $\alpha-2\beta$ 反键

$S_{1/2}:l=0,s=\frac{1}{2},j=\frac{1}{2}$

$$\left|\frac{1}{2}\frac{1}{2}\right\rangle_{j,m_j}=\left|0\frac{1}{2}\frac{1}{2}\frac{1}{2}\right\rangle_{l,s,j,m_j}=\left|0,\frac{1}{2},0,\frac{1}{2}\right\rangle_{l,s,m_l,m_s}=|s\uparrow\rangle$$

$$\left|\frac{1}{2},-\frac{1}{2}\right\rangle=\left|0,\frac{1}{2},\frac{1}{2},-\frac{1}{2}\right\rangle=\left|0,\frac{1}{2},0,-\frac{1}{2}\right\rangle=|s,\downarrow\rangle$$

$P_{3/2}:l=1,s=\frac{1}{2},j=\frac{3}{2}$

$$\left|\frac{3}{2}\frac{3}{2}\right\rangle=\left|1\frac{1}{2}1\frac{1}{2}\right\rangle=|P^+\uparrow\rangle$$

$$\left|\frac{3}{2}\frac{1}{2}\right\rangle=\frac{1}{\sqrt{3}}\left|1\frac{1}{2}1-\frac{1}{2}\right\rangle-\sqrt{\frac{2}{3}}\left|1\frac{1}{2}0\frac{1}{2}\right\rangle=\frac{1}{\sqrt{3}}|P^+\downarrow\rangle-\sqrt{\frac{2}{3}}|P^0\uparrow\rangle$$

$$\left|\frac{3}{2},-\frac{1}{2}\right\rangle=-\frac{1}{\sqrt{3}}\left|1,\frac{1}{2},-1,\frac{1}{2}\right\rangle-\sqrt{\frac{2}{3}}\left|1,\frac{1}{2},0,-\frac{1}{2}\right\rangle=-\frac{1}{\sqrt{3}}|P^-\uparrow\rangle-\sqrt{\frac{2}{3}}|P^0\downarrow\rangle$$

$$\left|\frac{3}{2},-\frac{3}{2}\right\rangle=-\left|1,\frac{1}{2},-1,-\frac{1}{2}\right\rangle=|P^-\downarrow\rangle$$

$P_{1/2}$ :

$$\left|\frac{1}{2}\frac{1}{2}\right\rangle=\sqrt{\frac{2}{3}}\left|1,\frac{1}{2},1,-\frac{1}{2}\right\rangle+\sqrt{\frac{1}{3}}\left|1,\frac{1}{2},0,\frac{1}{2}\right\rangle=\sqrt{\frac{2}{3}}|p^+\downarrow\rangle+\sqrt{\frac{1}{3}}|p^0\uparrow\rangle$$

$$\left|\frac{1}{2},-\frac{1}{2}\right\rangle=\sqrt{\frac{2}{3}}\left|1,\frac{1}{2},-1,\frac{1}{2}\right\rangle-\sqrt{\frac{1}{3}}\left|1,\frac{1}{2},0,-\frac{1}{2}\right\rangle=\sqrt{\frac{2}{3}}|p^-\uparrow\rangle-\sqrt{\frac{1}{3}}|p^0\downarrow\rangle$$

Sisyphus劈裂

相向电场  $\vec{e}=\hat{e}_x,\vec{e}'=\hat{e}_y,E_0=E_0'$

$$\text{总电场 } E(z, t) = E_0 \cos(\omega t - kz) \vec{e} + E'_0 \cos(\omega t + kz) = E^+(z) e^{-i\omega t} + E^-(z) e^{i\omega t}$$

$$\text{其中 } E^+(z) = \frac{1}{2} (E_0 \hat{e}_x e^{ikz} + E_0 \hat{e}_y e^{-ikz}) = \frac{E_0}{\sqrt{2}} (\vec{\varepsilon}_1 \cos kz - i \vec{\varepsilon}_2 \sin kz)$$

$$\vec{\varepsilon}_1 = \frac{\hat{e}_x + \hat{e}_y}{\sqrt{2}}, \quad \vec{\varepsilon}_2 = \frac{\hat{e}_y - \hat{e}_x}{\sqrt{2}}$$

$$z = 0: E^+(z) \propto \frac{\hat{e}_x + \hat{e}_y}{\sqrt{2}}, \text{ 线偏 } \vec{\varepsilon}_1$$

$$z = \frac{\lambda}{8}: E^+(z) \propto \vec{\varepsilon}_1 - i \varepsilon_2, \sigma^- \text{圆偏}$$

$$z = \frac{\lambda}{4}: E^+(z) \propto -i \vec{\varepsilon}_2, \text{ 线偏 } -\vec{\varepsilon}_2$$

$$z = \frac{3\lambda}{8}: E^+(z) \propto \vec{\varepsilon}_1 + i \vec{\varepsilon}_2, \sigma^+ \text{圆偏}$$

$$z = \frac{\lambda}{2}: E^+(z) \propto -\vec{\varepsilon}_1, \text{ 线偏 } -\vec{\varepsilon}_1$$

$$\text{Na: } ^2S_{1/2} \leftrightarrow ^2P_{3/2}, \text{ 记为 } g, e \text{ 偏振梯度}$$

$$\left| g_{-\frac{1}{2}} \right\rangle \xrightarrow{\sigma_+} \left| e_{+\frac{1}{2}} \right\rangle \propto \left( \frac{1}{\sqrt{3}} \right)^2 \quad \left| g_{\frac{1}{2}} \right\rangle \xrightarrow{\sigma_+} \left| e_{\frac{3}{2}} \right\rangle \propto 1$$

$$\delta E \propto |\langle f | H | i \rangle|^2 \quad P_{21} = \langle 2 | H | 1 \rangle, \Omega = P_{21} \frac{E_0}{\hbar}$$

$$\begin{cases} i \frac{dc_1}{dt} = -\frac{\Omega}{2} e^{i\delta t} c_2 \\ i \frac{dc_2}{dt} = -\frac{\Omega}{2} e^{-i\delta t} c_1 \end{cases} \quad \begin{pmatrix} c'_1 = c_1 \\ c'_2 = c_2 e^{i\delta t} \end{pmatrix} \implies \begin{cases} i \hbar \frac{dc'_1}{dt} = -\frac{\hbar \Omega}{2} c'_2 \\ i \hbar \frac{dc'_2}{dt} = -\frac{\hbar \Omega}{2} c'_1 + \hbar \delta c'_2 \end{cases}$$

$$\text{即 } i \hbar \begin{pmatrix} c'_1 \\ c'_2 \end{pmatrix} = H \begin{pmatrix} c'_1 \\ c'_2 \end{pmatrix}, \quad H = \begin{pmatrix} 0 & -\frac{\hbar \Omega}{2} \\ -\frac{\hbar \Omega}{2} & \hbar \delta \end{pmatrix}$$

$$E_{12} = \frac{\hbar(\delta \pm \sqrt{\delta^2 + \Omega^2})}{2} \quad \Omega \ll \delta \text{ 时 } \begin{cases} E_1 = -\frac{\hbar}{4} \frac{\Omega^2}{\delta} \\ E_2 = \hbar \delta + \frac{\hbar}{4} \frac{\Omega^2}{\delta} \end{cases}$$

$$\text{即 } \delta E_1 = -\frac{\hbar}{4} \frac{\Omega^2}{\delta}, \quad \delta E_2 = +\frac{\hbar}{4} \frac{\Omega^2}{\delta}$$

$$\text{平均力 } \vec{f} = \frac{\langle \Delta \vec{p} \rangle}{\Delta t} = \frac{1}{\Delta t} \langle \hbar \vec{k} (N_+ - N_-) + \sum_{sp} \hbar \vec{k}_{sp} \rangle = \hbar \vec{k} \frac{\langle N_+ \rangle - \langle N_- \rangle}{\Delta t}$$

$$\text{由于 } \langle N_+ \rangle - \langle N_- \rangle = n_1 \Gamma_{12} \Delta t - n_2 \Gamma_{21} \Delta t, \text{ 且由平衡关系 } n_1 \Gamma_{12} = n_2 \Gamma_{21} + n_2 \Gamma_{sp}$$

$$\text{可知 } \langle N_+ \rangle - \langle N_- \rangle = n_2 \Gamma_{sp} \Delta t, \text{ 即 } \vec{f} = \hbar \vec{k} n_2 \Gamma_{sp}$$

$$H = H_0 + H_1, \quad H_0 = \hbar \omega_1 |1\rangle\langle 1| + \hbar \omega_2 |2\rangle\langle 2|, \quad H_1 = -\frac{1}{2} \vec{\mu}_0 \cdot \vec{E} e^{i\omega t} |1\rangle\langle 2|$$

由刘维尔方程知

$$\dot{\rho}_{11} = \frac{1}{i\hbar} [(H_0 + H_1), \rho]_{11} - \frac{1}{T_{11}} (\rho_{11} - \rho_{11}^0)$$

$$\dot{\rho}_{22} = \frac{1}{i\hbar} [(H_0 + H_1), \rho]_{22} - \frac{1}{T_{22}} (\rho_{22} - \rho_{22}^0)$$

$$\dot{\rho}_{12} = \frac{1}{i\hbar} [(H_0 + H_1), \rho]_{12} - \frac{\rho_{12}}{T_{12}}$$

$$\dot{\rho}_{21} = \frac{1}{i\hbar} [(H_0 + H_1), \rho]_{21} - \frac{\rho_{21}}{T_{21}}$$

$$\text{其中 } T_{11} = T_{22} = T_1 = \frac{1}{\Gamma}, T_{12} = T_{21} = T_2 = \frac{2}{\Gamma}, \Gamma = \Gamma_{sp}$$

$$\text{无哈密顿量时 } \dot{\rho}_{ij} = -\frac{\rho_{ij} - \rho_{ij}^0}{T_{ij}}, \text{ 即 } \rho_{22} \sim e^{-\Gamma t}, c_2 \sim e^{-\frac{\Gamma}{2} t}, c_1 \sim 1, \rho_{12} \sim e^{-\frac{\Gamma}{2} t}$$

$$\text{计算哈密顿量项: } [H_0, \rho]_{ij} = (E_i - E_j) \rho_{ij}$$

$$[H_1, \rho]_{11} = (H_1)_{12}\rho_{21} - \rho_{12}(H_1)_{21} = (H_1)_{12}\rho_{21} - \rho_{21}^*(H_1)_{12}^* = 2i \operatorname{Im}[(H_1)_{12}\rho_{21}] = -[H_1, \rho]_{22}$$

$$[H_1, \rho]_{12} = (H_1)_{11}\rho_{12} + (H_1)_{12}\rho_{12} - \rho_{11}(H_1)_{12} - \rho_{12}(H_1)_{22} = (H_1)_{12}(\rho_{22} - \rho_{11}) = -[H_1, \rho]_{21}^*$$

其中用到了  $(H_1)_{ii} = 0$ , 令  $\rho_{12} = \bar{\rho}_{12}e^{i\omega t}$ ,  $\rho_{21} = \bar{\rho}_{21}e^{-i\omega t}$

$$\text{则 } 2 \operatorname{Im}[(H_1)_{12}\rho_{21}] = \frac{i}{2} \vec{\mu}_{12} \cdot \vec{E}(\bar{\rho}_{21} - \bar{\rho}_{12})$$

初始  $\rho_{11}(0) = 1, \rho_{22}(0) = 0$ , 且  $k_B T \ll E_2 - E_1$ , 则

$$\begin{cases} \dot{\rho}_{11} = i \frac{\vec{\mu}_{12} \cdot \vec{E}}{2\hbar} (\bar{\rho}_{21} - \bar{\rho}_{12}) - \Gamma(\rho_{11} - 1) \\ \dot{\rho}_{22} = -i \frac{\vec{\mu}_{12} \cdot \vec{E}}{2\hbar} (\bar{\rho}_{21} - \bar{\rho}_{12}) - \Gamma\rho_{22} \\ \dot{\rho}_{12} = i(\omega_0 - \omega)\bar{\rho}_{12} + i \frac{\vec{\mu}_{12} \cdot \vec{E}}{2\hbar} (\rho_{22} - \rho_{11}) - \frac{\Gamma}{2}\bar{\rho}_{12} \\ \dot{\rho}_{21} = -i(\omega_0 - \omega)\bar{\rho}_{21} - i \frac{\vec{\mu}_{12} \cdot \vec{E}}{2\hbar} (\rho_{22} - \rho_{11}) - \frac{\Gamma}{2}\bar{\rho}_{21} \end{cases}$$

其中  $\omega_0 \approx (\omega_2 - \omega_1) + k\hat{e}_{\vec{k}} \cdot \vec{v} = \omega_{21} + k\hat{e}_{\vec{k}} \cdot \vec{v}$

考虑稳态并令  $n_2 = \rho_{22}$  得

$$\begin{cases} \Gamma n_2 = -i \frac{\vec{\mu} \cdot \vec{E}}{2\hbar} (\bar{\rho}_{21} - \bar{\rho}_{12}) \\ -i(\omega_0 - \omega)\bar{\rho}_{12} + i \frac{\vec{\mu} \cdot \vec{E}}{2\hbar} (2n_2 - 1) = \frac{\Gamma\bar{\rho}_{12}}{2} \\ -i(\omega_0 - \omega)\bar{\rho}_{21} - i \frac{\vec{\mu} \cdot \vec{E}}{2\hbar} (2n_2 - 1) = \frac{\Gamma\bar{\rho}_{21}}{2} \end{cases}$$

解出

$$n_2 = \frac{(\frac{\vec{\mu} \cdot \vec{E}}{2\hbar})^2}{[(\omega_0 - \omega)^2 + (\frac{\Gamma}{2})^2] + 2(\frac{\vec{\mu} \cdot \vec{E}}{2\hbar})^2}$$

令  $\Delta = \omega - \omega_{21}$  得

$$n_2 = \frac{(\frac{\vec{\mu} \cdot \vec{E}}{2\hbar})^2}{(\Delta - k\hat{e}_{\vec{k}} \cdot \vec{v})^2 + 2(\frac{\vec{\mu} \cdot \vec{E}}{2\hbar})^2 + (\frac{\Gamma}{2})^2}$$

相应

$$\vec{f} = \hbar \vec{k} \Gamma_{sp} n_2 = \frac{\hbar \vec{k} \Gamma (\frac{\vec{\mu} \cdot \vec{E}}{2\hbar})^2}{(\Delta - k\hat{e}_{\vec{k}} \cdot \vec{v})^2 + 2(\frac{\vec{\mu} \cdot \vec{E}}{2\hbar})^2 + (\frac{\Gamma}{2})^2}$$

考虑正反两方向知

$$\vec{f}_s = \vec{f}_{\vec{k}} + \vec{f}_{-\vec{k}} = \hbar \vec{k} \Gamma \left[ \frac{(\frac{\vec{\mu} \cdot \vec{E}}{\hbar \Gamma})^2}{\frac{(\Delta - k\hat{e}_{\vec{k}} \cdot \vec{v})^2}{(\frac{\Gamma}{2})^2} + 2(\frac{\vec{\mu} \cdot \vec{E}}{\hbar \Gamma})^2 + 1} - \frac{(\frac{\vec{\mu} \cdot \vec{E}}{\hbar \Gamma})^2}{\frac{(\Delta + k\hat{e}_{\vec{k}} \cdot \vec{v})^2}{(\frac{\Gamma}{2})^2} + 2(\frac{\vec{\mu} \cdot \vec{E}}{\hbar \Gamma})^2 + 1} \right]$$

$kv \ll \Delta$  时

$$\vec{f} = \left\{ \frac{\delta \hbar \vec{k}}{\Gamma} \frac{\Delta (\frac{\mu_{12} E}{\hbar \Gamma})^2 \vec{k}}{[\frac{\Delta^2}{(\frac{\Gamma}{2})^2} + 2(\frac{\vec{\mu} \cdot \vec{E}}{\hbar \Gamma})^2 + 1]^2} \right\} \cdot \vec{v} \propto \Delta \vec{k} \vec{k} \cdot \vec{v}$$

原子钟 GPS系统  $(x - A_i)^2 + (y - B_i)^2 + (z - C_i)^2 - [c(T_i - d)]^2 = 0$

$$\text{接收 } \tilde{T}_0 = T_0 + \frac{D}{c}, \quad D' = c(T_1 - T'_0)$$

$$\text{Cs钟 } N = 10^6, T = 0.9s \quad \Delta|\omega - \omega_0| = \frac{1}{2T\sqrt{N}} = 5.6 \times 10^{-4} Hz, \\ \omega_0 \sim 2\pi \times 9.2GHz, \frac{\Delta\omega}{\omega} \sim 10^{-14}, \Delta T \sim 8.6 \times 10^{-10}s, c\Delta T = 0.25m$$

$$\text{以}g\text{下降的电梯中, 光下落}H, \text{光源}v = gt = g\frac{H}{c} \quad \omega_B = \omega_A(1 + \frac{v}{c}) = \omega_A(1 + \frac{gH}{c^2})$$

$$\text{原子跃迁装置Cs, Rb} \implies \text{频率发生器(转换)} \implies \text{晶振} \implies \text{标准频率输出}$$

$$\text{跃迁过程 } |1\rangle \rightarrow |2\rangle, \frac{N_2 - N_1}{N} \propto f(|\omega - \omega_0| \frac{T}{2})$$

$$\text{Cs: } S_e = \frac{1}{2}, S_n = I = \frac{7}{2}, J = S = \frac{1}{2}, F = I + J = 4, 3$$

$$\text{在}1m\text{尺度上下振动, 周期}T = 2\sqrt{\frac{2H}{g}} = 0.9s, \text{频率劈裂}\omega = \omega_0 \pm \frac{\pi}{2T}, \Delta\omega = 1.7Hz$$

$$\text{测}N\text{次: } \begin{cases} T(F=4) & p \\ F(F=3) & 1-p=q \end{cases} \quad \langle T \rangle = Np, \Delta^2 = Npq, \Delta = \sqrt{Npq}$$

$$\text{设}\varphi = (\omega - \omega_0)\frac{T}{2}, \text{则}\langle N_1 \rangle = N \sin^2 \varphi, \langle N_2 \rangle = N \cos^2 \varphi$$

$$\text{则}\Delta N_1 = \Delta N_2 = \sqrt{N} |\sin \varphi \cos \varphi|, \frac{\Delta(N_2 - N_1)}{N} = \frac{1}{\sqrt{N}} |\sin 2\varphi|$$

$$\text{同时 } \frac{N_2 - N_1}{N} = \cos 2\varphi, \quad \frac{\Delta(N_2 - N_1)}{N} = 2 |\sin 2\varphi| \Delta\varphi$$

$$\text{由以上两种等价可知}\Delta\varphi = \frac{1}{2\sqrt{N}} \implies \Delta|\omega - \omega_0| = \frac{1}{2T\sqrt{N}}$$

$$\text{令}|1\rangle, |2\rangle = \{|F=3, 4\rangle\}, \text{量子态}|\psi(t)\rangle = \alpha|1\rangle + \beta|2\rangle = \cos \frac{\theta}{2}|1\rangle + e^{i\varphi} \sin \frac{\theta}{2}|2\rangle$$

$$\text{在电场}E = E_0 \cos(\omega t + \varphi)$$

$$\begin{cases} \alpha(t + \varepsilon) = e^{i\frac{\delta t}{2}} \left[ \alpha(t) \left( \cos \frac{\Omega_R \varepsilon}{2} + i \cos \theta \sin \frac{\Omega_R \varepsilon}{2} \right) + \beta(t) e^{i(\delta t + \varphi)} \left( -i \sin \theta \sin \frac{\Omega_R \varepsilon}{2} \right) \right] \\ \beta(t + \varepsilon) = e^{-i\frac{\delta t}{2}} \left[ \alpha(t) e^{-i(\delta t + \varphi)} \left( -i \sin \theta \sin \frac{\Omega_R \varepsilon}{2} \right) + \beta(t) \left( \cos \frac{\Omega_R \varepsilon}{2} - i \cos \theta \sin \frac{\Omega_R \varepsilon}{2} \right) \right] \end{cases}$$

$$\text{其中}\sin \theta = \frac{\Omega}{\Omega_R}, \cos \theta = -\frac{\delta}{\Omega_R}, \text{失谐}\delta = \omega - \omega_0, \text{拉比频率}\Omega_R = \sqrt{\Omega^2 + \delta^2}, \Omega = \frac{\langle 2|\mu \cdot E|1\rangle}{\hbar} \\ \Omega_R \sim MHz - GHz$$

$$\text{在}\delta = 0\text{时, } \sin \theta = 1, \cos \theta = 1, \begin{cases} \alpha(t + \varepsilon) = \alpha(t) \cos \frac{\Omega \varepsilon}{2} + \beta(t) e^{i\varphi} (-i \sin \frac{\Omega \varepsilon}{2}) \\ \beta(t + \varepsilon) = \alpha(t) e^{-i\varphi} (-i \sin \frac{\Omega \varepsilon}{2}) + \beta(t) \cos \frac{\Omega \varepsilon}{2} \end{cases}$$

$$\text{取}\Omega \varepsilon = \pi \text{即}\pi\text{-操作: } \alpha(t + \varepsilon) = -i\beta e^{i\varphi}, \beta(t + \varepsilon) = -i\alpha e^{i\varphi}, \text{即}O_\pi = \begin{pmatrix} 0 & -i \\ -i & 0 \end{pmatrix}$$

$$\text{同理}O_{\frac{\pi}{2}} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -ie^{i\varphi} \\ -ie^{-i\varphi} & 1 \end{pmatrix}$$

$$\text{对于}\delta = 0\text{的情况, 取}\alpha(0) = 1, \beta(0) = 0, \Omega_R \varepsilon = \frac{\pi}{2}, \begin{cases} \alpha(\varepsilon) = e^{i\frac{\delta \varepsilon}{2}} \frac{1+i\cos \theta}{\sqrt{2}} \\ \beta(\varepsilon) = -e^{-i\frac{\delta \varepsilon}{2}} e^{-i\varphi} \frac{i\sin \theta}{\sqrt{2}} \end{cases}$$

$$T\text{上升并回落: } \beta(\varepsilon + T + \varepsilon) = -ie^{-i\frac{\delta T}{2}} e^{-i\delta \varepsilon} e^{-i\varphi} \cos \frac{\delta T}{2} \text{ 即} |\beta(\varepsilon + T + \varepsilon)|^2 = \frac{1+\cos \delta T}{2}$$

$$\text{L, S, I 的耦合: } J = L + S, F = I + J = (L + S) + I$$

$$\text{对}^{87}\text{Rb}, I = S_n = \frac{3}{2}, J = S_e = \frac{1}{2}$$

$$\alpha_{hf} I \cdot J = \alpha_{nf} \frac{(I+J)^2 - I^2 - J^2}{2} = \frac{\alpha_{nf}}{2} (F^2 - I^2 - J^2) = \frac{\alpha_{nf}}{2} [F(F+1) - I(I+1) - J(J+1)]$$

$$\alpha^2 = \begin{cases} \text{hyperfine} & 10^8 \sim 10^9 Hz \\ \text{soc} & 10^{10} \sim 10^{11} Hz (meV) \\ \text{Coulomb} & 10^{14} Hz (eV) \end{cases}$$

$$H_{Zeeman} = B(\mu_B g_s S_z + \mu_N g_I I_z), \quad B \rightarrow \infty, H_N^2 \ll H_e^2$$

$$\text{SI: } \mu_B = \frac{e\hbar}{2m}, \mu_N = \frac{e\hbar}{2m_p} \quad \text{CGS: } \mu_B = \frac{e\hbar}{2mc}, \mu_N = \frac{e\hbar}{2m_p c}$$

$$H_{Zeeman}(B \rightarrow \infty) \sim B \mu_B g_s S_z$$

$$\nabla \cdot \vec{B} = 0, \nabla \times \vec{B} = 0 \implies \nabla^2 \vec{B} = 0 \quad |B| \text{ 没有极大值, HFS(超精细态) 不能被磁阱束缚}$$

$$|\vec{B}| = \sqrt{B_x^2 + B_y^2 + B_z^2}, \text{ 而}$$

$$\begin{aligned} \partial_x^2 |\vec{B}| &= -\frac{1}{|\vec{B}|^3} (B_i \partial_x B_i)^2 + \frac{1}{|\vec{B}|} \left[ \sum_i (\partial_x B_i)^2 + B_i \partial_x^2 B_i \right] \\ &\geq -\frac{1}{|\vec{B}|^3} (B_i B_i) \left[ \sum_i (\partial_x B_i)^2 \right] + \frac{1}{|\vec{B}|} \left[ \sum_i (\partial_x B_i)^2 + B_i \partial_x^2 B_i \right] \\ &= -\frac{1}{|\vec{B}|} B_i \partial_x^2 B_i \end{aligned}$$

$$\text{即 } \nabla^2 |\vec{B}| \geq -\frac{1}{|\vec{B}|} (B_i \nabla^2 B_i) = 0, \text{ 故 } |\vec{B}| \text{ 只有极小值}$$

$$\nabla^2 \vec{B} = 0 \implies \nabla^2 B_x = \nabla^2 B_y = \nabla^2 B_z = 0$$

$$\text{例如 } B = B_0(x, y, -2z) H(\vec{r}) = \alpha_{hf} I \cdot J + \vec{B}(\vec{r}) \cdot (\mu_B g_s \vec{S} + \mu_N g_N \vec{I})$$

$$\text{对角化 } U^\dagger(r) H(r) U(r) = \text{diag}\{\Lambda_1 \cdots \Lambda_q\} |B(\vec{r})|$$

$$\text{令 } H' = U^\dagger H U, \tilde{\psi} = U^\dagger \psi \text{ 有 } i\hbar \frac{\partial}{\partial t} \tilde{\psi} = H' \tilde{\psi}$$

$$\text{及 } U^\dagger p U = \vec{p} - \vec{A}, \quad \vec{A} = i\hbar U^\dagger(r) \nabla U(\vec{r}) \quad \text{即 } \frac{1}{2m} p^2 \rightarrow \frac{1}{2m} (\vec{p} - \vec{A})^2$$

$$\text{最后得到 } i\hbar \frac{\partial \tilde{\psi}}{\partial t} = \left[ \frac{1}{2m} (-i\hbar \nabla - \vec{A})^2 + \Lambda(r) \right] \tilde{\psi}, \text{ 其中 } \Lambda(r) = U^\dagger(\vec{r}) H_s(\vec{r}) U(\vec{r})$$

$$\text{对偶核 } ap + bn \leftrightarrow an + bp \quad V_{p-p} \approx V_{p-n} \approx V_{n-n}$$

$$\text{isospin } I = \frac{1}{2} \quad \begin{pmatrix} p \\ n \end{pmatrix} \quad p : I_s = \frac{1}{2}, \uparrow \quad n : I_s = -\frac{1}{2}, \downarrow$$

$$\text{双原子和多原子分子} \quad \text{电子-转动: spin-rot} \quad \text{电子-振动: SSB, Higgs} \quad \text{振动-转动: Coriolis}$$

$$H_N = -\frac{\hbar^2}{2m_a} \nabla_a^2 - \frac{\hbar^2}{2m_b} \nabla_b^2 + U(R)$$

$$H = H^{rot} + H^{vib}, \quad H^{rot} = \frac{1}{2} \Omega^T I \Omega = \frac{L^2}{2\mu R^2}$$

$$H^{vib} = -\frac{\hbar^2}{2\mu} \nabla^2 + U(R), \quad \psi(R, \theta, \varphi) = F(R) Y_J^\mu(\theta, \varphi)$$

$$G(R) = RF(R), \quad -\frac{\hbar^2}{2\mu} G'' + \left[ \frac{J(J+1)\hbar^2}{2\mu R^2} + U(R) - E \right] G(R) = 0$$

$$\text{令 } R - R_e = q, \quad U(R) = U_0 + \frac{1}{2} k q^2 \quad \text{记 } S(q) = G(R) \text{ 则}$$

$$-\frac{\hbar^2}{2\mu} S''(q) + \frac{1}{2} (k q^2 - W) S(q) = 0, \quad W = E - U(R_e) - \frac{J(J+1)\hbar^2}{2\mu R_e^2}$$

$$\text{得 } S_\nu(q) = \left(\frac{\alpha}{\pi}\right)^{\frac{1}{4}} \frac{1}{\sqrt{2^\nu \nu!}} H_\nu(\sqrt{\alpha} q) e^{-\frac{1}{2}\alpha q^2}, \quad \alpha = \frac{4\pi\nu_e\mu}{h}, \nu_e = \frac{1}{2\pi} \sqrt{\frac{k}{\mu}}$$



$$\text{考虑转动部分 } H = -\frac{\hbar^2}{2\mu} \frac{d^2}{dq^2} + \frac{1}{2} k q^2 + \frac{J^2}{2\mu R_e^2} - q \frac{J^2}{\mu R_e^3}$$

$$\text{即 } H = -\frac{\hbar^2}{2\mu} \frac{d^2}{dq^2} + \frac{1}{2} k \left( q - \frac{J^2}{\mu k R_e^2} \right)^2 - \frac{J^4}{2\mu^2 k R_e^6} + \frac{J^2}{2\mu R_e^2}$$

$$\text{Huang-Rhys电声耦合理论 Franck-Condon: } |\langle \nu' | H | \nu \rangle|^2 \propto |\langle \nu' | \nu \rangle|$$

$$\mu = \mu_e + \mu_N, \text{而}$$

$$\begin{aligned} \langle \mu \rangle &= \int \psi_{el}'^* \psi_{\nu'}' (\mu_e + \mu_N) \psi_{el} \psi_{\nu} d\mathbf{r} dR \\ &= \int \psi_{\nu'}'^* \psi_{\nu} dR \int \psi_{el}'^* \mu_e \psi_{el} d\mathbf{r} + \int \psi_{el}'^* \psi_{el} d\mathbf{r} \int \psi_{\nu'}' \mu_N \psi_{\nu} dR \\ &= {}_e \langle \nu' | \nu \rangle_q \int \psi_{el}'^* \mu_e \psi_{el} d\mathbf{r} \end{aligned}$$

总哈密顿量

$$H = -\frac{\hbar^2}{2m} \sum_i^{el} \nabla_i^2 - \frac{\hbar^2}{2} \sum_{\alpha}^{Nucl} \frac{1}{m_{\alpha}} \nabla_{\alpha}^2 + \sum_{\alpha} \sum_{p>\alpha} \frac{Z_{\alpha} Z_{\beta} e^2}{R_{\alpha\beta}} - \sum_{\alpha} \sum_i \frac{Z_{\alpha} e^2}{r_{i\alpha}} + \sum_i \sum_{j>i} \frac{e^2}{r_{ij}}$$

$$H(r_i, R_{\alpha}) \psi(r_i, R_{\alpha}) = E(r_i, R_{\alpha})$$

$$\text{Born-Oppenheimer Ansatz(预解式) } \psi(r_i, R_{\alpha}) = \sum_I \psi_{el,I}(r_i, R_{\alpha}) \psi_{N,I}(R_{\alpha})$$

$$H_{el} \psi_{el,I} = E_O(R_{\alpha}) \psi_{el,I}, \quad U_I = E_{el,I} + V_{NN}, \quad E_{el,I} \text{为1,4,5部分}, \quad V_{NN} \text{为3部分}$$

$$H_N = -\frac{\hbar^2}{2} \sum_{\alpha} \frac{1}{m_{\alpha}} \nabla_{\alpha}^2 + U_I(R_{\alpha})$$

$$I = 0:$$

$$\begin{aligned} -i \frac{\partial}{\partial t} \psi_{N,0} &= -\frac{\hbar^2}{2m_{\alpha}} \left( \frac{\partial^2}{\partial R_{\alpha}^2} \psi_{N,0} + 2 \frac{\partial \psi_{N,0}}{\partial R_{\alpha}} \sum_I \langle \psi_{el,0} | \frac{\partial}{\partial R_{\alpha}} | \psi_{el,0} \rangle + \langle \psi_{el,0} | \frac{\partial^2}{\partial R_{\alpha}^2} | \psi_{el,0} \rangle \psi_{N,0} \right) \\ &\quad + U_0(R_{\alpha}) \psi_{N,0} \end{aligned}$$

$$\text{其中 } \langle \psi_{el,0} | \frac{\partial^2}{\partial R_l^2} | \psi_{el,0} \rangle \text{称为Born-Huang connection}$$

$$R_0 \rightarrow R'_0(\hat{D}): \text{电声耦合激发 } \omega \rightarrow \omega'(\hat{S}): \text{压缩态 } \{S_i\} \rightarrow \{S'_i\}(\hat{U}): \text{模式切换}$$

$$\xi = 1, \dots, f \quad C_{\xi}^{(r)} = \sqrt{\frac{\omega}{2\hbar}} q_{\xi} + i \frac{1}{\sqrt{2\hbar\omega}} p_{\xi} \quad \text{即} \begin{cases} q_{\xi} = \sqrt{\frac{\hbar}{2\omega}} (c_{\xi} + c_{\xi}^{\dagger}) \\ p_{\xi} = -i \sqrt{\frac{\hbar\omega}{2}} (c_{\xi} - c_{\xi}^{\dagger}) \end{cases}$$

$$\text{引入} \begin{cases} Q_{\xi} = q_{\xi} \sqrt{\frac{2\omega}{\hbar}} = c_{\xi} + c_{\xi}^{\dagger} \\ P_{\xi} = p_{\xi} \sqrt{\frac{2}{\hbar\omega}} = -i(c_{\xi} - c_{\xi}^{\dagger}) \end{cases}$$

$$\text{本征态 } |v_1 \cdots v_f\rangle, \text{对双原子分子记为 } |\nu_1\rangle \quad c_{\xi} |v_{\xi}\rangle = \sqrt{v_{\xi}} |v_{\xi} - 1\rangle, c_{\xi}^{\dagger} |v_{\xi}\rangle = \sqrt{v_{\xi} + 1} |v_{\xi} + 1\rangle$$

$$H_{e/g} = U(q_{\xi,0}^{(e/g)}) + \frac{1}{2} \sum_{\zeta} (p_{\zeta}^2 + \omega_{\zeta}^2 (q_{\zeta} - q_{0,\zeta}^{(e/g)})^2)$$

$$\text{定义 } g_a^{(\zeta)} = -\sqrt{\frac{\omega}{2\hbar}} q_{\zeta,0}^{(a)}, \quad a = e, g \text{ 则}$$

$$H_a = U_a^{(0)} + \sum_{\zeta} \hbar \omega_{\zeta} (c_{\zeta}^{\dagger} c_{\zeta} + \frac{1}{2}) + \sum_{\zeta} \hbar \omega_{\zeta} (g_a(\zeta) (c_{\zeta}^{\dagger} + c_{\zeta}) + g_a^2(\zeta))$$

$$|g\rangle, |e\rangle, q = 0 \quad \text{位移为 } q_{\zeta,0}^{(a)}$$

$$\text{将含} g \text{的项看作微扰, } H = \sum_{\zeta} \hbar \omega_{\zeta} (c_{\zeta}^{\dagger} c_{\zeta} + \frac{1}{2}) |v_{\zeta}\rangle = \frac{1}{\sqrt{v_{\zeta}!}} (c_{\zeta}^{\dagger})^v |0\rangle$$

$$\text{相应 } \psi_{a(=e,g),v}(q_{\zeta} - q_{\zeta}^{(a)}) = \sum_{n=0}^{\infty} \frac{(-q_{\zeta}^{(a)})^n}{n!} \frac{d^n}{dq_{\zeta}^n} \psi_{a,v}(q_{\zeta}) = e^{-\frac{i}{\hbar} q_{\zeta}^{(a)} \hat{p}_{\zeta}} \psi_{a,v}(q_{\zeta})$$

$$\text{由 } -\frac{i}{\hbar} q_{\zeta}^{(a)} \hat{p}_{\zeta} = g_a(\zeta)(c_{\zeta} - c_{\zeta}^{\dagger}), \text{ 可知平移算符}$$

$$D^{\dagger}(g_a(\zeta)) = e^{g_a(\zeta)(c_{\zeta} - c_{\zeta}^{\dagger})}, \text{ 且 } D(g_a(\zeta)) |0\rangle = |g_a(\zeta)\rangle$$

$$\text{即 } |v_{\zeta}^{(a)}\rangle = \frac{1}{\sqrt{v_{\zeta}!}} D^{\dagger}(g_a(\zeta)) (\hat{c}_{\zeta}^{\dagger})^{v_{\zeta}} |0\rangle = D^{\dagger}(g_a(\zeta)) |v_{\zeta}\rangle$$

$$\text{平移算符满足 } D^{\dagger}(g) = D(-g) = D^{-1}(g)$$

$$\text{对 } c, c^{\dagger} \text{ 的位移 } D^{\dagger}(g) c^{\dagger} D(g) = e^{g(c-c^{\dagger})} c^{\dagger} e^{-g(c-c^{\dagger})}$$

$$\text{利用 BCH 公式 } e^A B e^{-A} = B + [A, B] + \frac{1}{2!} [A, [A, B]] + \frac{1}{3!} [A, [A, [A, B]]] + \dots$$

$$\text{可得 } D^{\dagger}(g) c^{\dagger} D(g) = c^{\dagger} + g, \text{ 即 } H_a = U_a^{(0)} + \sum_{\zeta} \hbar \omega_{\zeta} [(c_{\zeta}^{\dagger} + g_a(\zeta))(c_{\zeta} + g_a(\zeta)) + \frac{1}{2}]$$

$$\text{投影 } \langle \psi_{e\mu} | \psi_{g\nu} \rangle = \langle \mu | D(g_e) D^{\dagger}(g_g) | \nu \rangle, \text{ 其中}$$

$$D(g_e) D^{\dagger}(g_g) = e^{-g_e(c-c^{\dagger})} e^{g_g(c-c^{\dagger})} = e^{\Delta g_{eg} c^{\dagger}} e^{-\Delta g_{eg} c} e^{-\frac{\Delta g_{eg}^2}{2}}$$

$$\text{其中 } \Delta g_{eg} = g_e - g_g = -\sqrt{\frac{\omega}{2\hbar}} (q_o^{(e)} - q_o^{(g)})$$

$$\text{而 } e^{-\Delta g_{eg} c} | \nu \rangle = \sum_{n=0}^{\nu} \frac{(-\Delta g_{eg})^n}{n!} c^n | \nu \rangle = \sum_{n=0}^{\nu} \frac{(-\Delta g_{eg})^n}{n!} \sqrt{\frac{\nu!}{(\nu-n)!}} | \nu - n \rangle$$

由此得到

$$\langle \psi_{e\nu'} | \psi_{g\nu} \rangle = e^{-\frac{\Delta g_{eg}^2}{2}} \sum_{m=0}^{\nu'} \sum_{n=0}^{\nu} \frac{(-)^n (\Delta g_{eg})^{m+n}}{m! n!} \sqrt{\frac{\nu'!}{(m-\nu')!} \frac{\nu!}{(n-\nu)!}} \delta_{\nu'-m, \nu-n}$$

$$\text{对 } \nu = 0 \implies n = 0, \text{ 定义 } \Delta g_{eg}^2 = \frac{\omega}{2\hbar} (\Delta q_o^2) = S$$

$$\text{则 } |\langle \psi_{e\nu'} | \psi_{g0} \rangle|^2 = e^{-S} \left( \sum_{m=0} \frac{(\sqrt{S})^m}{m!} \sqrt{\frac{\nu'!}{(m-\nu')!}} \delta_{\nu'-m, 0} \right)^2 = \frac{e^{-S} S^{\nu'}}{\nu'!} \text{ 即 } |\langle \nu | 0 \rangle|^2 = \frac{e^{-S} S^{\nu}}{\nu!}, S \ll 1$$

时, 对  $\nu \neq 0$  将压低投影概率

$$\hat{D}^{\dagger}(g) \hat{q} \hat{D}(g) = \hat{q} + g \text{ 平移 } \hat{S}^{\dagger}(\lambda) \hat{q} \hat{S}(\lambda) = e^{\Lambda} \hat{q} \text{ 压缩 (拉伸)} \quad \hat{U}^{\dagger}(0) \hat{q} \hat{U}(0) = \hat{O} \hat{q}$$

$$\hat{q}_{e,0} = A q_{g,0} + d = \hat{W}^{\dagger} q_{g,0} \hat{W}, \quad \hat{W} \approx \hat{U}(0) \hat{S}(\lambda) \hat{D}(g)$$

$$\text{由 } \langle \nu'_e | \nu_g \rangle = \langle 0_e | \prod_{s=1}^f \frac{c_{e,\zeta}^{\nu_{\zeta}}}{\sqrt{\nu_{\zeta}!}} | \nu_g \rangle, \text{ 可知}$$

$$\begin{aligned} \langle \nu'_1 \nu'_2 \dots | \nu_1 \nu_2 \dots \rangle &= \langle 0_g | \hat{W} \left( \hat{W}^T \prod_{\zeta=1}^f \frac{c_{g,\zeta}^{\nu_{\zeta}}}{\sqrt{\nu_{\zeta}!}} \hat{W} \right) | \nu_g \rangle \\ &= \langle 0_g | \prod_{\zeta=1}^f \frac{c_{g,\zeta}^{\nu_{\zeta}}}{\sqrt{\nu_{\zeta}!}} \hat{W} | \nu_g \rangle \\ &= \langle \nu'_g | \hat{W} | \nu_g \rangle \end{aligned}$$

$$\text{考虑电磁波, } (x, p) \leftrightarrow (E, \varphi), \quad \tilde{E} = E e^{i\varphi}$$

$$\hat{\vec{E}}(\vec{r}, t) = \hat{\vec{E}}^{(+)}(\vec{r}, t) + \hat{\vec{E}}^{(-)}(\vec{r}, t), \quad (E^{(-)}) = (E^{(+)})^{\dagger}$$

$E^{(+)}$ : photon absorption,  $n \rightarrow n - 1$     $E^{(-)}$ : photon emission,  $n \rightarrow n + 1$

$$\text{即 } E^{(+)} \sim \hat{a} e^{-i\omega t}, E^{(-)} \sim \hat{a}^\dagger e^{i\omega t}, \hat{\vec{E}}^{(+)} |vac\rangle = 0, \langle vac | \hat{\vec{E}}^{(-)} = 0$$

$$\text{一阶关联函数 } G_{\mu\nu}^{(1)}(\vec{r}t, \vec{r}'t') = \text{Tr}[\hat{\rho} \hat{E}_\mu^{(-)} \hat{E}_\nu^{(+)}] = \mathcal{E}_\mu^*(\vec{r}t) \mathcal{E}_\nu(\vec{r}'t')$$

给定  $(\omega, \vec{k}, \hat{e}^{(\lambda)}, \vec{\mathcal{E}})$ , 单模自由空间电磁波满足

$$\nabla^2 \vec{u}_k + \frac{\omega_k^2}{c^2} \vec{u}_k = 0, \begin{cases} \nabla \cdot \vec{u}_k = 0 \\ \int \vec{u}_k^*(\vec{r}) \vec{u}_l(\vec{r}) d\vec{r} = \delta_{kl} \end{cases}$$

$$\text{得 } \vec{u}_k(\vec{r}) = \frac{1}{L^{\frac{3}{2}}} \hat{e}^{(\lambda)} e^{i\vec{k} \cdot \vec{r}}, \lambda = 1, 2 \text{ 为偏振自由度}$$

$$\text{对应 } \hat{A} = c \sum_k \sqrt{\frac{\hbar}{2\omega_k}} [\hat{a}_k \vec{u}_k(\vec{r}) e^{-i\omega_k t} + \hat{a}_k^\dagger \vec{u}_k(\vec{r}) e^{i\omega_k t}]$$

$$\text{因此 } \hat{H} = \frac{1}{2} \int (E^2 + B^2) d\vec{r} = \frac{1}{2} \sum_k \hbar \omega_k (\hat{a}_k^\dagger \hat{a}_k + \hat{a}_k \hat{a}_k^\dagger) = \sum_k \hbar \omega_k (n_k + \frac{1}{2})$$

$$\text{对易关系 } [\hat{a}_k, \hat{a}_{k'}^\dagger] = \delta_{k'k}, \quad [\hat{a}_k, \hat{a}_{k'}] = [\hat{a}_k^\dagger, \hat{a}_{k'}^\dagger] = 0$$

$$\text{本征态 } \hat{a}_k |0\rangle_k = 0, \quad |n_k\rangle_k = \frac{(\hat{a}_k^\dagger)^{n_k}}{(n_k!)^{\frac{1}{2}}} |0\rangle_k, \quad \begin{cases} \hat{a}_k |n_k\rangle_k = \sqrt{n_k} |n_k - 1\rangle_k \\ \hat{a}_k^\dagger |n_k\rangle_k = \sqrt{n_k + 1} |n_k + 1\rangle_k \\ \hat{a}_k^\dagger \hat{a}_k |n_k\rangle_k = n_k |n_k\rangle \end{cases}$$

$$\text{电场 } \hat{\vec{E}} = -\frac{1}{c} \frac{d\hat{A}}{dt}, \quad \hat{\vec{E}}^{(+)}(\vec{r}t) = i \sum_k \sqrt{\frac{\hbar \omega_k}{2}} \hat{a}_k \vec{u}_k(\vec{r}) e^{-i\omega_k t}$$

电场算符的本征态: 考虑相干态  $\hat{a} |\alpha\rangle = \alpha |\alpha\rangle$

$$\sqrt{n+1} \langle n+1 | \alpha \rangle = \alpha \langle n | \alpha \rangle \implies \langle n | \alpha \rangle = \frac{\alpha^n}{\sqrt{n!}} \langle 0 | \alpha \rangle$$

$$|\alpha\rangle = \sum_n |n\rangle \langle n | \alpha \rangle = \langle 0 | \alpha \rangle \sum_n \frac{\alpha^n}{\sqrt{n!}} |n\rangle$$

$$\text{而 } \langle \alpha | \alpha \rangle = |\langle 0 | \alpha \rangle|^2 \sum_n \frac{|\alpha|^{2n}}{n!} = |\langle 0 | \alpha \rangle|^2 e^{|\alpha|^2}$$

$$\text{归一化: } \langle \alpha | \alpha \rangle = 1 \implies \langle 0 | \alpha \rangle = e^{-\frac{|\alpha|^2}{2}} \implies |\alpha\rangle = e^{-\frac{|\alpha|^2}{2}} \sum_n \frac{\alpha^n}{\sqrt{n!}} |n\rangle$$

$$\text{由 } q = \sqrt{\frac{\hbar}{2\omega}} (\hat{a}^\dagger + \hat{a}), p = i\sqrt{\frac{\hbar\omega}{2}} (\hat{a}^\dagger - \hat{a}), [q, p] = i\hbar$$

$$\text{可得 } \langle \alpha | q | \alpha \rangle = \sqrt{\frac{2\hbar}{\omega}} \text{Re}\alpha, \quad \langle \alpha | p | \alpha \rangle = \sqrt{2\hbar\omega} \text{Im}\alpha$$

考虑  $\hat{a} \vec{u}_k(\vec{r}) = \alpha \vec{u}_k(\vec{r}) = \mathcal{E}_\alpha u_k(\vec{r})$ , 含相互作用的哈密顿量

$$\hat{H} = \hat{H}_{rad} + \hat{V}(t) = \hbar\omega(\hat{a}^\dagger \hat{a} + \frac{1}{2}) + i\hbar(f(t)\hat{a}^\dagger - f^*(t)\hat{a}), \quad f(t) = f_0 e^{-i\omega t}$$

$$\text{相互作用表象中 } V_I(t) = e^{\frac{iH_0 t}{\hbar}} i\hbar(f(t)\hat{a}^\dagger - f^*(t)\hat{a}) e^{-\frac{iH_0 t}{\hbar}} = i\hbar(f_0 \hat{a}^\dagger - f_0^* \hat{a})$$

$$\text{演化算符 } i\hbar \frac{\partial}{\partial t} U_I = V_I U_I \implies U_I(t) = e^{(f_0 \hat{a}^\dagger - f_0^* \hat{a})t}$$

$$\text{相应 } |\psi(t)\rangle_I = e^{(f_0 t) \hat{a}^\dagger - (f_0^* t) \hat{a}} |0\rangle = D(f_0 t) |0\rangle = e^{-\frac{|f_0|^2 t^2}{2}} e^{f_0 a^\dagger t} |0\rangle \quad \text{是相干态}$$

$$D(\alpha) = e^{\alpha \hat{a}^\dagger - \alpha^* \hat{a}}, \quad |\alpha\rangle = D(\alpha) |0\rangle$$

$$\text{单位分解: } 1 = \sum_n |n\rangle \langle n| = \frac{1}{\pi} \int d^2\alpha |\alpha\rangle \langle \alpha|$$

$$\text{相干态展开 } |\psi\rangle = \int d^2\alpha F(\alpha) |\alpha\rangle$$

$$\text{压缩相干态 } H = \frac{p^2}{2} + \frac{1}{2} \omega^2 q^2 = \frac{p^2}{2} + \frac{1}{2} C q^2, \quad H' = \frac{p^2}{2} + \frac{1}{2} \omega'^2 q^2 = \frac{p^2}{2} + \frac{1}{2} C' q^2$$

$$H' = \hbar\omega(\hat{a}^\dagger\hat{a} + \frac{1}{2}) + \frac{1}{2}C_1q^2 = \hbar\tilde{\omega}(\hat{a}^\dagger\hat{a} + \frac{1}{2}) + \frac{1}{2}\tilde{C}_1(\hat{a}^{\dagger 2} + \hat{a}^2)$$

$$\text{压缩算符 } \hat{S}(\zeta) = e^{\frac{\zeta\hat{a}^{\dagger 2} - \zeta^*\hat{a}^2}{2}}, \zeta = re^{i\varphi}$$

$$\hat{Q} = \frac{1}{\sqrt{2}}(\hat{a} + \hat{a}^\dagger), \hat{P} = \frac{1}{\sqrt{2}i}(\hat{a} - \hat{a}^\dagger),$$

$$\text{对压缩态 } \hat{Q}(r) = \hat{S}^\dagger(r)\hat{Q}(0)\hat{S}(r) = Q(0)e^{-r}, \quad \hat{P}(r) = \hat{S}^\dagger(r)\hat{P}(0)\hat{S}(r) = P(0)e^r$$

$$\text{升降算符 } \hat{a}(r) = \hat{a} \cosh r - \hat{a}^\dagger \sinh r, \quad \hat{a}^\dagger(r) = -\hat{a} \sinh r + \hat{a}^\dagger \cosh r$$

$$\text{考虑频率突变的振子 } H(t) = \hbar\omega(t)(\hat{a}^\dagger\hat{a} + \frac{1}{2}), \quad \omega(t) = \begin{cases} \omega_0, & t < 0 \\ \omega_1, & t \geq 0 \end{cases}$$

$$\text{升降算符 } \begin{cases} \hat{a}^\dagger = \frac{1}{\sqrt{2}}(\sqrt{\frac{m\omega_0}{\hbar}}\hat{Q} - i\sqrt{\frac{1}{\hbar m\omega_0}}\hat{P}) \\ \hat{a} = \frac{1}{\sqrt{2}}(\sqrt{\frac{m\omega_0}{\hbar}}\hat{Q} + i\sqrt{\frac{1}{\hbar m\omega_0}}\hat{P}) \end{cases}$$

演化

$$\begin{aligned} \hat{a}^\dagger(t) &= e^{i\omega_1 t} \hat{a}^\dagger(0) \\ &= e^{i\omega_1 t} \frac{1}{\sqrt{2}} \left( \sqrt{\frac{m\omega_1}{\hbar}} \hat{Q} - i \sqrt{\frac{1}{m\hbar\omega_1}} \hat{P} \right) \\ &= e^{i\omega_1 t} \frac{1}{\sqrt{2}} \left[ \sqrt{\frac{\omega_1}{\omega_0}} \sqrt{\frac{m\omega_0}{\hbar}} \hat{Q} - i \sqrt{\frac{\omega_0}{\omega_1}} \sqrt{\frac{1}{m\hbar\omega_0}} \hat{P} \right] \\ &= e^{i\omega_1 t} \left( \frac{\omega_1 + \omega_0}{2\sqrt{\omega_0\omega_1}} \hat{a}^\dagger + \frac{\omega_1 - \omega_0}{2\sqrt{\omega_0\omega_1}} \hat{a} \right) \\ &= U^*(t) \hat{a}^\dagger + V^*(t) \hat{a} \end{aligned}$$

写成压缩参数形式

$$\begin{cases} \hat{\tilde{a}}^\dagger(0) = \cosh r \hat{a}^\dagger - \sinh r \hat{a} \\ \hat{\tilde{a}}(0) = \cosh r \hat{a} + \sinh r \hat{a}^\dagger \end{cases}$$

$$\text{其中压缩参数 } r = \operatorname{arctanh} \frac{\omega_0 - \omega_1}{\omega_0 + \omega_1}, S = -10 \lg e^{-2r} (dB)$$

$$\text{以及 } \langle Q^2 \rangle(t) = \frac{\hbar}{2m\omega_1} \langle (\tilde{a}(t) + \tilde{a}^\dagger(t))^2 \rangle = \frac{\hbar}{m\omega_1} \langle |U(t) + V^*(t)|^2 (n + \frac{1}{2}) \rangle,$$

$$\text{其中 } \langle n + \frac{1}{2} \rangle = \frac{1}{e^{\beta\hbar\omega_0} - 1} + \frac{1}{2} = \frac{1}{2} \coth \frac{\beta\hbar\omega_0}{2},$$

$$\text{以及 } |U(t) + V^*(t)|^2 = \frac{\omega_1}{2\omega_0} \left[ \left(1 + \frac{\omega_0^2}{\omega_1^2}\right) + \left(1 - \frac{\omega_0^2}{\omega_1^2}\right) \cos 2\omega_1 t \right]$$

Fiber bundle & vibration

$$\text{考虑甲烷分子, } M = \{c, H_1, H_2, H_3, H_4\}, \text{ 对应 } E_c, E_1, E_2, E_3, E_4$$

$$\text{给定位移函数 } f \text{ 即平衡位置附近的位移, } f(c) \in E_c, f(i) \in E_i, i = 1, 2, 3, 4$$

抽象化:

$$M = \{x\}, \text{ 定义 vector bundle, 矢量空间的集合 } \{E_x\}, \forall x \in M$$

$$E = \bigcup_{x \in M} E_x \text{ 是 } M \text{ 上的 VBun, 不是矢量空间}$$

$$\pi: E \rightarrow M, \pi(v) = x, v \in E_x \quad E_x = \pi^{-1}(x) \text{ 是 } x \text{ 点的纤维}$$

$$(E, M) \text{ vBun 截面 } f \text{ 是 } M \text{ 上的函数, } f(x) \in E_x, \forall x \in E_x$$

$$(f_1 + f_2)(x) = f_1(x) + f_2(x), \quad (cf)(x) = c(f(x)), \Gamma = \{f_i\}$$

$$\dim(\Gamma(E)) = \sum_{x \in M} \dim(E_x)$$

$$G \text{ 作用于 } M, E \text{ 是 } M \text{ 上 } \text{Bun}_V, G \text{ 作用如下:}$$

$$(1) a \in G, E_x \rightarrow E_{ax} \text{ 是线性的; } (2) \pi : E \rightarrow M \text{ 是 } G\text{-态射, } a\pi(v) = \pi(av)$$

$$\Gamma(E) \text{ 是 } 3N \text{ 维线性空间, 可作为 } G \text{ 的表示空间}$$

$$\text{对于不变原子 } ax = x, a(v_x)_j = \sum_i (A_x)_{ij} (v_x)_i \implies af_{v_{xj}} = \sum_i (A_x)_{ij} f_{v_{xi}}$$

$$R(a) \text{ 在 } \Gamma(E) \text{ 截面上作用的特征标 } \chi = \sum_{x,i} (A_x)_{ii}$$

$$Frob_a(M) = \{x \in M | ax = x\}$$

$$\text{Frobenius 不动点定理: 对 } a \in G, \chi_E(a) \text{ 特征标为 } \chi_E(a) = \sum_{x \in Frob_a(M)} \text{Tr}(a : E_x \rightarrow E_x)$$

$$\text{特征标表:}$$

$T_a$	$E$	$8C_3$	$3C_2$	$6\sigma_d$	$6S_4$
$A_1$	1	1	1	1	1
$A_2$	1	1	1	-1	-1
$E$	2	-1	2	0	0
$R_xR_yR_z(T_1)$	3	0	-1	-1	1
$xyz(T_2)$	3	0	-1	-1	1
$\Gamma$	3	0	-1	1	-1

$$\chi(C_n^m) = N_{C_n^m}^{inv} [1 + 2 \cos \frac{2n\pi}{m}], \chi(E) = 3N, \chi(S_n) = \chi(C_n \sigma_n) = N_{S_n}^{inv} (-1 + 2 \cos \frac{2\pi}{n})$$

$$\chi(i) = -3N_i^{inv}, \chi(\sigma) = N_{\sigma}^{inv}, \chi(\sigma_d) = N_{\sigma_d}^{inv}$$

$$\Gamma = A_1 \oplus E \oplus T_1 \oplus 3T_2, \quad \Gamma_{vib} = T - T_1 - T_2 = A_1 \oplus E \oplus 2T_2$$

$$\text{分子的转动}$$

$$\text{双原子 } \vec{J} = \vec{N} + \vec{L} + \vec{S}, \vec{N} \text{ 为机械部分}$$

$$\hat{H} = B\hat{N}^2 = B(N_x^2 + N_y^2) = B(\vec{J} - \vec{L} - \vec{S})_{x,y}^2$$

$$\begin{aligned} \hat{H}_{rot} = & B(J^2 - J_z^2) + B(S^2 - S_z^2) + B(L^2 - L_z^2) \\ & - B(J^+L^- + J^-L^+) - B(J^+S^- + J^-S^+) + B(L^+S^- + L^-S^+) \end{aligned}$$

$$\hat{H}_{SO} = A\vec{L} \cdot \vec{S} = AL_zS_z + \frac{1}{2}A(L^+S^- + L^-S^+)$$

$$\text{角动量升降 } J^\mp |\Omega JM\rangle = \hbar \sqrt{J(J+1) - \Omega(\Omega \pm 1)} |\Omega \pm 1, JM\rangle$$

$$\text{Anomalous commutator } [\hat{J}_x, \hat{J}_y] = -i\hbar \hat{J}_z$$

$$\hat{e}_i, i = X, Y, Z \quad \hat{u}^\alpha, \alpha = x, y, z \quad \text{方向余弦 } \lambda_{\alpha i} = \hat{u}^\alpha \cdot \hat{e}_i$$

$$[J_\alpha, J_\beta] = -i\hbar \varepsilon_{\alpha\beta\gamma} K_\gamma, \quad [J_x, J_y] = [\lambda_{xi} J_i, \lambda_{yj} J_j]$$

利用  $\lambda_{xY}\lambda_{yZ} - \lambda_{xZ}\lambda_{yY} = \lambda_{zZ}$  可得  $[\hat{J}_x, \hat{J}_y] = -i\hbar\hat{J}_z$

考虑  $^2\Sigma^+$ :  $\left| ^2\Sigma_{\pm\frac{1}{2}} \right\rangle = \left| \Lambda = 0, S = \frac{1}{2}, \Sigma = \pm\frac{1}{2} \right\rangle \left| \Omega = \pm\frac{1}{2}, JM \right\rangle$

$$\left\langle ^2\Sigma_{\frac{1}{2}} \left| \hat{H}_{rot} \right| ^2\Sigma_{\frac{1}{2}} \right\rangle = \left\langle ^2\Sigma_{-\frac{1}{2}} \left| \hat{H}_{rot} \right| ^2\Sigma_{-\frac{1}{2}} \right\rangle = B(J + \frac{1}{2})^2$$

$$\left\langle ^2\Sigma_{-\frac{1}{2}} \left| \hat{H}_{rot} \right| ^2\Sigma_{\frac{1}{2}} \right\rangle = -B(J + \frac{1}{2})$$

$$\text{即 } H = \begin{pmatrix} B(J + \frac{1}{2})^2 & -B(J + \frac{1}{2}) \\ -B(J + \frac{1}{2}) & B(J + \frac{1}{2})^2 \end{pmatrix}$$

新基  $\left| ^2\Sigma^+(e, f) \right\rangle = \frac{\left| ^2\Sigma_{\frac{1}{2}}^+ \right\rangle \pm \left| ^2\Sigma_{-\frac{1}{2}}^+ \right\rangle}{\sqrt{2}}$ , 在此基下对角化

$$H = \begin{pmatrix} B(J + \frac{1}{2})^2 - B(J - \frac{1}{2}) & 0 \\ 0 & B(J + \frac{1}{2})^2 - B(J + \frac{1}{2}) \end{pmatrix}$$

$$\vec{N} = \vec{J} - \vec{S}, N = J - \frac{1}{2}, |e\rangle; N = J + \frac{1}{2}, |f\rangle$$

$$F_1(e) = BN(N+1) = F_2(f)$$

加入电场,  $\mu \cdot E = \mu_z E_z$

$$\mu_Z^{lab} = \mu_i \cos iZ = (\alpha_{zz} E_z)_{lab} = \alpha_{ii} E_i \cos(iZ) = \alpha_{ii} E_Z \cos^2(iZ) = E_z (\alpha_{xx} + (\alpha_{yy} - \alpha_{xx}) \cos^2(zZ))$$

考虑水分子,  $\hat{H} = \hat{H}_{rot} + \hat{H}' = \hat{H}_{rot} - E_i^*(t) \alpha_{ij} E_j(t)$ ,  $\alpha_{ij}$  为实验室系中

$$\text{即 } \hat{H}' = -\frac{1}{2} \sum_{JM} (-)^{J+M} U(t)_M^{[J]} \alpha_{-M}^{[J]}, U(t)_M^{[J]} = [E^*(t)^{[1]} \times E(t)^{[1]}]_M^{[J]}$$

$$\text{其中 } T_q^{[1]} = \begin{cases} -\frac{T_x + iT_y}{\sqrt{2}} & q = 1 \\ T_z & q = 0 \\ \frac{T_x - iT_y}{\sqrt{2}} & q = -1 \end{cases}$$

$$\text{张量积 } \{E^{[1]} \times E^{[1]}\}_M^{[J]} = \sum_{q_1 q_2} \langle 1q_1 1q_2 | 11JM \rangle E_{q_1}^{[1]} E_{q_2}^{[1]}$$

$$(E^{[1]} \times E^{[1]})_0^0 = \sum_{q_1 q_2} \begin{pmatrix} 1 & 1 & 0 \\ q_1 & q_2 & 0 \end{pmatrix} E_{q_1}^{[1]} E_{q_2}^{[1]}, \quad \begin{pmatrix} 1 & 1 & 0 \\ q_1 & q_2 & 0 \end{pmatrix} = (-)^{1-q_1} \delta_{q_1-q_2} \frac{1}{\sqrt{3}}$$

$$E(t) = (\pm E_x \sin(k_y y - \omega t), 0, E_z \cos(k_y y - \omega t)) = \frac{1}{2}(\pm E_x, 0, E_z)$$

$$(E^{[1]} \times E^{[1]})_0^0 = -\frac{1}{\sqrt{3}}(E_x^2(t) + E_z^2(t))$$

$$|E(t)|^2 = E_x^2 \sin^2(k_y y - \omega t) + E_z \cos^2(k_y y - \omega t) = 4\pi\alpha I$$

$$a = \frac{E_x}{\sqrt{E_x^2 + E_z^2}}, b = \frac{E_z}{\sqrt{E_x^2 + E_z^2}}, E = \sqrt{4\pi\alpha I}(\pm a, 0, b)$$

$$U_0^{[0]} = -\frac{1}{\sqrt{3}}(E_x^2(t) + E_z^2(t)) = -\sqrt{\frac{1}{3}}4\pi\alpha I, U_0^{[2]}(t) = \sqrt{\frac{1}{6}}(2E_z^2(t) - E_x^2(t)) = \sqrt{\frac{1}{6}}4\pi\alpha I(2 - 3a^2)$$

$$U_{\pm 1}^{[2]} = \mp E_x(t) E_z(t) = 0 \quad U_{\pm 2}^{[2]} = \frac{1}{2} E_x^2(t) = 2\pi\alpha I a^2 \quad (\text{时间平均})$$

$$\alpha^{(p)} = \begin{pmatrix} \alpha_R & & \\ & \alpha_S & \\ & & \alpha_T \end{pmatrix}$$

$$\alpha_0^{(0)} = -\sqrt{\frac{1}{3}}(\alpha_R + \alpha_S + \alpha_T) \quad \alpha_0^{(2)} = \sqrt{\frac{1}{6}}(2\alpha_T - \alpha_R - \alpha_S)$$

$$\alpha_{\pm 2}^{(2)} = \frac{1}{2}(\alpha_R - \alpha_S \pm i(\alpha_{RS} + \alpha_{SR})) \quad \alpha_0^{(1)} = \frac{i}{\sqrt{2}}(\alpha_{RS} - \alpha_{SR})$$

$$\alpha_{\pm 1}^{(1)} = \frac{1}{2}(\alpha_{TR} - \alpha_{RT} \mp i(\alpha_{ST} - \alpha_{TS}))$$

$$\alpha_{\pm 1}^{(2)} = \mp \frac{1}{2}(\alpha_{RT} + \alpha_{TR} - i(\alpha_{ST} + \alpha_{TS}))$$

$$\alpha_0^{(0)L} = D_{00}^{(0)}(R_{PL}\alpha_{(0)}^{(0)P}) = \alpha_0^{(0)P}$$

$$\alpha_0^{(2)L} = D_{Q0}^{(2)}(R_{PL})\alpha_Q^{(2)P} = (D_{20}^{(2)} + D_{-20}^{(2)})(R_{PL})\alpha_2^{(2)P} + D_{00}^{(2)}(R_{PL})\alpha_0^{(2)P}$$

$$\alpha_{\pm 1}^{(2)L} = D_{Q\pm 1}^{(2)}(R_{PL})\alpha_Q^{(2)}, \quad \alpha_{\pm 2}^{(2)L} = D_{Q\pm 2}^{(2)}(R_{PL})\alpha_Q^{(2)}$$

$$H_L = -\frac{1}{2}E_i^{(L)}E_j^{(L)}\alpha_{ij}^{(L)} = -\frac{1}{2}U_{ij}\alpha_{ij} = -\frac{1}{2}\sum_{JM}(-)^{J+M}U_M^{(J)}\alpha_{-M}^{(J)}, J=0,2$$

$$\text{即 } H_L = -\frac{1}{2}[U_0^{(0)}\alpha_0^{(0)} + U_0^{(0)}\alpha_0^{(0)} + U_2^{(2)}(\alpha_2^{(2)} + \alpha_{-2}^{(2)})]$$

考虑转动

$$\alpha_0^{(2)L} = D_{m0}^{(2)}(0, \beta, 0)\alpha_m^{(2)P} = \sqrt{\frac{4\pi}{3}}Y_{2m}^*(\beta, 0)\alpha_m^{(2)P} = \sqrt{\frac{3}{2}}\cos^2\theta(\alpha_{zz} - \alpha_{xx}) - \sqrt{\frac{1}{6}}(\alpha_{zz} - \alpha_{xx})$$

$$\alpha_0^{(2)P} = \sqrt{\frac{1}{6}}(2\alpha_T - \alpha_R - \alpha_S) = \sqrt{\frac{2}{3}}(\alpha_{zz} - \alpha_{xx})$$

$$\alpha_{\pm 2}^{(2)} = \frac{1}{2}(\alpha_R - \alpha_S \pm i(\alpha_{RS} + \alpha_{SR})) = 0$$

$$\alpha_0^{(0)L} = \alpha_0^{(0)P} = -\sqrt{\frac{1}{3}}(\alpha_{zz} - 2\alpha_{xx})$$

$$U_0^{(2)L} = \sqrt{\frac{1}{6}}(2E_z^2 - E_x^2) = \sqrt{\frac{2}{3}}E_z^2, \quad E_x = 0$$

$$U_0^{(0)L} = -\sqrt{\frac{1}{3}}E_z^2$$

$$\text{即 } H_L = -\frac{1}{2}\cos^2\theta E_z^2(\alpha_{zz} - \alpha_{xx}) + E_z^2\alpha_{xx}$$

$$\text{转动部分 } H = \frac{J_a^2}{2I_{aa}} + \frac{J_b^2}{2I_{bb}} + \frac{J_c^2}{2I_{cc}} = AJ_a^2 + BJ_b^2 + CJ_c^2, \quad J_a = I_{aa}\omega_a$$

$$\text{设 } A \geq B \geq C \text{ 即 } I_{aa} \leq I_{bb} \leq I_{cc}$$

$$\text{线型: } I_{cc} = I_{bb} > I_{aa} = 0 \quad \text{球对称分子: } I_{aa} = I_{bb} = I_{cc}$$

$$\text{prolate: } A > B = C, I_{aa} < I_{bb} = I_{cc} \quad \text{oblate: } A = B > C, I_{aa} = I_{bb} < I_{cc}$$

$$\hat{H}^{(pro)} = AJ_a^2 + B(J_b^2 + J_c^2) = BJ^2 + (A - B)J_a^2$$

$$\hat{H}^{(obl)} = B(J^2 - J_c^2) + CJ_c^2 = BJ^2 + (C - B)J_c^2$$

$$J^2 D_{mk}^{*J} = J(J+1)\hbar^2 D_{mk}^{*J}, \quad J_z D_{mk}^{*J} = k\hbar D_{mk}^J$$

$$E^{(pro)} = BJ(J+1)\hbar^2 + (A - B)k^2\hbar^2, \quad E^{(obl)} = BJ(J+1)\hbar^2 - (B - C)k^2\hbar^2$$

$$A \neq B \neq C: \text{ 不对称陀螺分子} \quad \text{不对称度 } K = \frac{2B-A-C}{A-C}$$

$$\text{长陀螺 } A > B = C, K = -1 \quad \text{扁陀螺 } A = B > C, K = 1$$

$$H_{rot}^{obl} = AJ_a^2 + BJ_b^2 + CJ_c^2 = \frac{A-B}{4}(J_+^2 + J_-^2) + \frac{A+B}{4}(J_+J_- + J_-J_+) + CJ_z^2$$

$$\text{得到 } H_{rot}^{obl} = \frac{A+B}{2}J^2 + (C - \frac{A+B}{2})J_z^2 + \frac{A-B}{4}(J_+^2 + J_-^2)$$

$$\text{同理 } H_{rot}^{pro} = \frac{B+C}{2} + (A - \frac{B+C}{2})J_z^2 + \frac{B-C}{4}(J_+^2 + J_-^2)$$

$|JM\tau\rangle = \sum_{k\geq 0} a^J_{k\tau} [|JKM\rangle + (-)^\tau |J,-KM\rangle]$

不同k有混合，k不是好量子数

$V = \{E, R_a(\pi), R_b(\pi), R_c(\pi)\} \cong C_{2v}$  克莱因四元群

$C_{2v}$	$V$	$E$	$R_a(\pi)$	$R_b(\pi)$	$R_c(\pi)$
$A_1$	$A$	1	1	1	1
$B_1$	$B_a$	1	1	-1	-1
$A_2$	$B_b$	1	-1	1	-1
$B_2$	$B_c$	1	-1	-1	1

$R_z(\pi) |JKM\rangle = e^{ik\pi} |JKM\rangle = (-)^k |JKM\rangle$

$R_x(\pi) |JKM\rangle = (-)^J |J,-KM\rangle \quad R_y(\pi) |JKM\rangle = (-)^J e^{-ik\pi} |J,-KM\rangle$

长陀螺极限  $a = z$

$K_a$	$\Gamma^{rot}$	$E$	$R_a$	$R_b$	$R_c$
0 (J even)	$A$	1	1	1	1
0 (J odd)	$B_a$	1	1	-1	-1
odd	$B_b \oplus B_c$	2	-2	0	0
even	$A \oplus B_a$	2	2	0	0

扁陀螺极限  $c = z$

$K_c$	$\Gamma^{rot}$	$E$	$R_a$	$R_b$	$R_c$
0 (J even)	$A$	1	1	1	1
0 (J odd)	$B_c$	1	-1	-1	1
odd	$B_a \oplus B_b$	2	0	0	-2
even	$A \oplus B_c$	2	0	0	2

Fano共振

$|\psi_f\rangle = \alpha |\phi_0\rangle^a + \int dE_b \beta_b |\psi_0^b\rangle$

束缚态 $a: \hat{H}_0 |\phi_0^a\rangle = E_a |\phi_0^a\rangle$  连续态 $b: \hat{H}_0 |\phi_0^b\rangle = E_b |\phi_0^b\rangle$

$\hat{H} = \hat{H}_0 + \hat{V}, \quad \langle \phi_0^a | \hat{H} | \phi_0^a \rangle = E_a, \langle \phi_0^b | \hat{H} | \phi_0^{b'} \rangle = E_b \delta(E_{b'} - E_b), \langle \phi_0^a | \hat{H} | \phi_0^b \rangle = V_b$

$\hat{H} |\psi\rangle = E |\psi\rangle \implies \begin{cases} \alpha E_a + \int dE_b \beta_b V_b = E \alpha \\ \alpha V_{b'}^* + \beta_{b'} E_{b'} = \beta_{b'} E \end{cases}$

Fano-Dirac Ansatz  $\beta_{b'} = \frac{\alpha V_{b'}^*}{E - E_{b'}} + Z_E \delta(E - E_{b'}) V_{b'} \alpha = \alpha V_{b'}^* \left[ \frac{1}{E - E_{b'}} + Z_E \delta(E - E_{b'}) \right]$

即  $E_a + \int dE_b \frac{|V_b|^2}{E - E_b} + Z_E |V_E|^2 = E$ , 积分项记为  $F(E)$

$\implies Z_E = \frac{E - (E_a + F(E))}{|V_E|^2} = \frac{E - E_R}{\frac{\pi \Gamma}{2}} = \pi \varepsilon, \varepsilon = 0 \text{共振}$



$$\alpha=\frac{\sin \delta}{\pi V_E}, \beta_{b'}=\frac{V_b}{\pi V_E}\frac{\sin \delta}{E-E_b}-\cos \delta \delta(E-E_{b'}), \tan \delta=-\frac{\pi}{2\varepsilon}$$

$$\text{从而}|\psi(E)\rangle=\frac{\sin \delta}{\pi V_E}|\phi\rangle-\cos \delta\left|\phi_0^E\right\rangle,\quad|\phi\rangle=\left|\phi_0^a\right\rangle+\int \mathrm{d} E_b \frac{V_b}{E-E_b}\left|\phi_0^b\right\rangle$$

$$\left\langle\psi(E)\right| H\left|GS\right\rangle=-\cos \delta\left\langle\phi_0^a\right| H\left|GS\right\rangle+\frac{\sin \delta}{\pi V_E^*}\left\langle\phi\right| H\left|GS\right\rangle$$

$$\text{进而}\frac{\left|\left\langle\psi(E)\right| H\left|GS\right\rangle\right|^2}{\left|\left\langle\phi_0^E\right| H\left|GS\right\rangle\right|^2}=\left(-\cos \delta+\frac{\sin \delta}{\pi V_E^*} \frac{\left\langle\phi\right| H\left|GS\right\rangle}{\left\langle\phi_0^E\right| H\left|GS\right\rangle}\right)^2,\quad \text{引入Fano } q \text{ 参数}$$

$$\frac{\left|\left\langle\psi(E)\right| H\left|GS\right\rangle\right|^2}{\left|\left\langle\phi_0^E\right| H\left|GS\right\rangle\right|^2}=\left(-\cos \delta+q \sin \delta\right)^2=\frac{(\varepsilon+q)^2}{1+\varepsilon^2},\quad \varepsilon=\frac{E-E_R}{\frac{\pi \Gamma}{2}}$$